## Exercise

Please hand in this paper to the instructor before the end of the lecture.

Name:	
Student number:	Date
	Date.

**Q.** Say a point (x, y) in the world-coordinate-system is mapped to point (x', y') in the camera-coordinate-system. Furthermore, we know that  $(x, y) \neq (0, 0)$  and that the camera sits at the origin of the world-coordinate-system.



Estimate the rotation angle  $\theta$  of the camera. Recall that the 2D rotation matrix is

$$R(\theta) = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}.$$