

# Least Squares

Computational Photography (CSCI 3240U) & Computer Vision (CSCI 4220U)

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<http://vclab.science.ontariotechu.ca>



Find accompanying notes at

<https://csundergrad.science.uoit.ca/courses/cv-notes/notebooks/15-least-squares.html>

<https://csundergrad.science.uoit.ca/courses/cv-notes/notebooks/16-robust-least-squares.html>

<https://csundergrad.science.uoit.ca/courses/cv-notes/notebooks/17-ransac.html>

<https://csgrad.science.uoit.ca/courses/ist/notebooks/linear-regression.html>



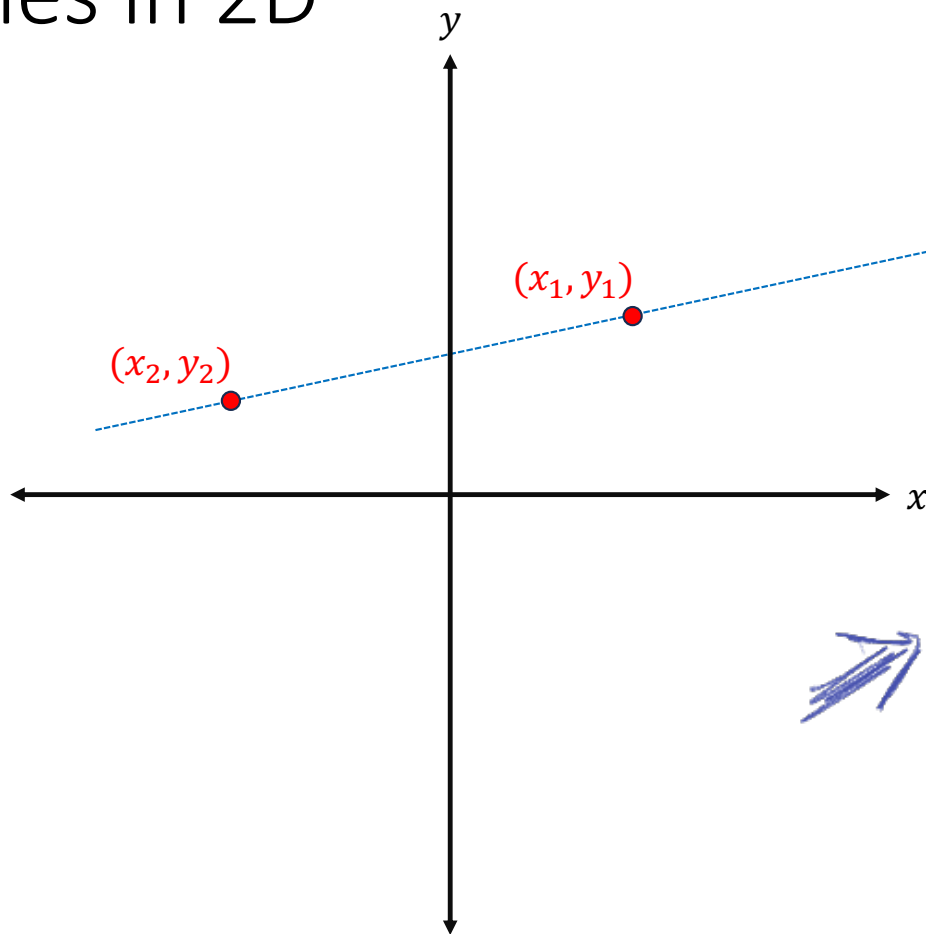
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# Lines in 2D

# Lines in 2D



output      input

Equation of a line in 2D

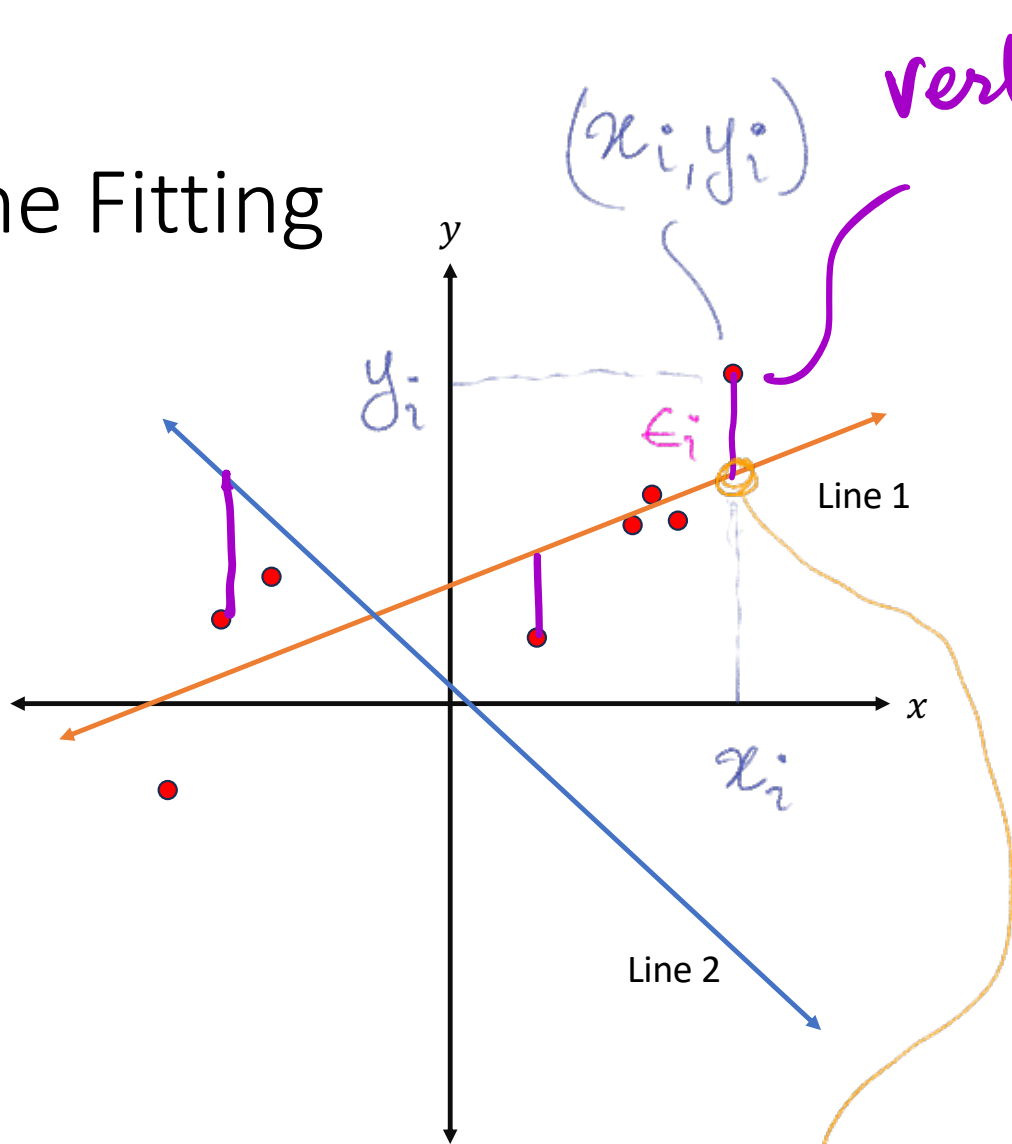
$$y = mx + c$$

parameters

$$\frac{y - y_1}{y_2 - y_1} = \frac{x - x_1}{x_2 - x_1}$$

$$\begin{bmatrix} x_1 \\ y_1 \\ 1 \end{bmatrix} \times \begin{bmatrix} x_2 \\ y_2 \\ 1 \end{bmatrix} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

# Line Fitting



vertical distances

Which of the two lines better represents the data?

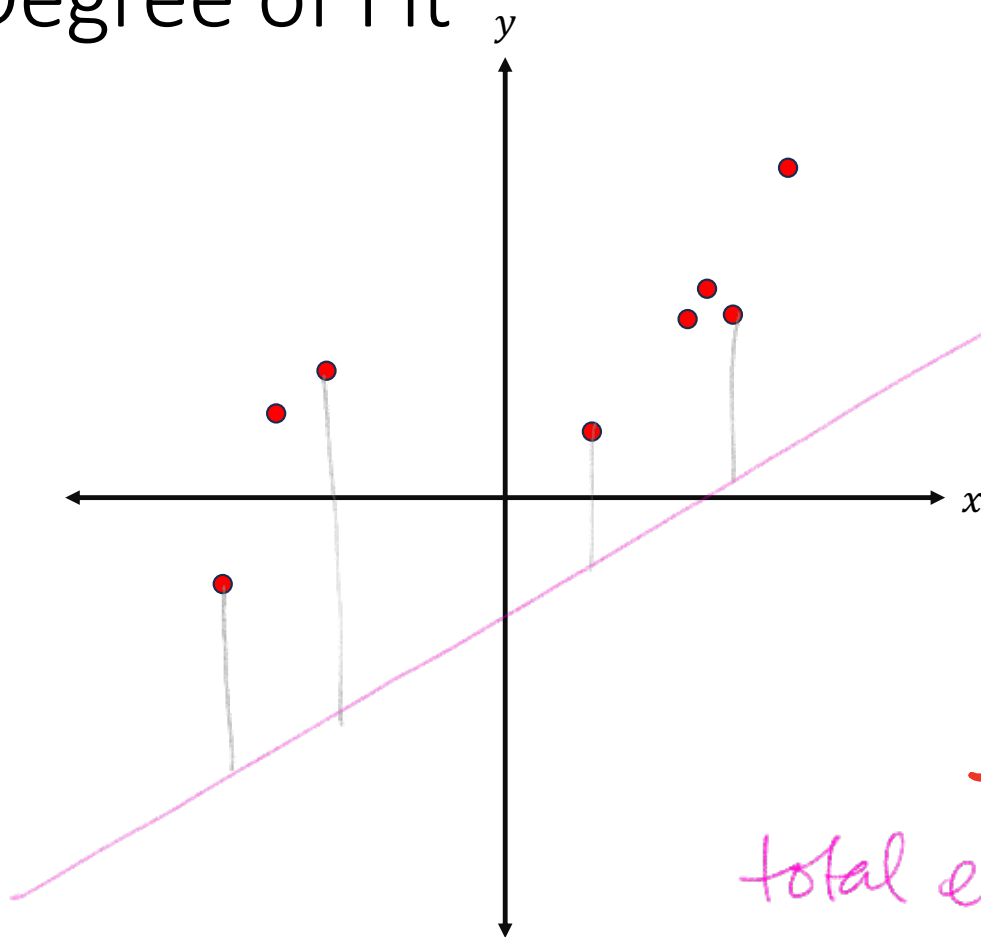
Line 1 seems to represent data better than Line 2.

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$$\epsilon_i = (y_i - (m x_i + b))^2$$



# Degree of Fit



## Mean Squared Error (MSE)

lower value

→ better fit

$m, b$

$$E_i = (y_i - mx_i - b)^2$$

$$\text{total error} = \sum_i E_i$$

# Least Squares Fitting (2D Lines)

Given

$$(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$$

Estimate  $m$  and  $b$  to setup the 2D line

$$y = mx + c$$

By minimizing MSE

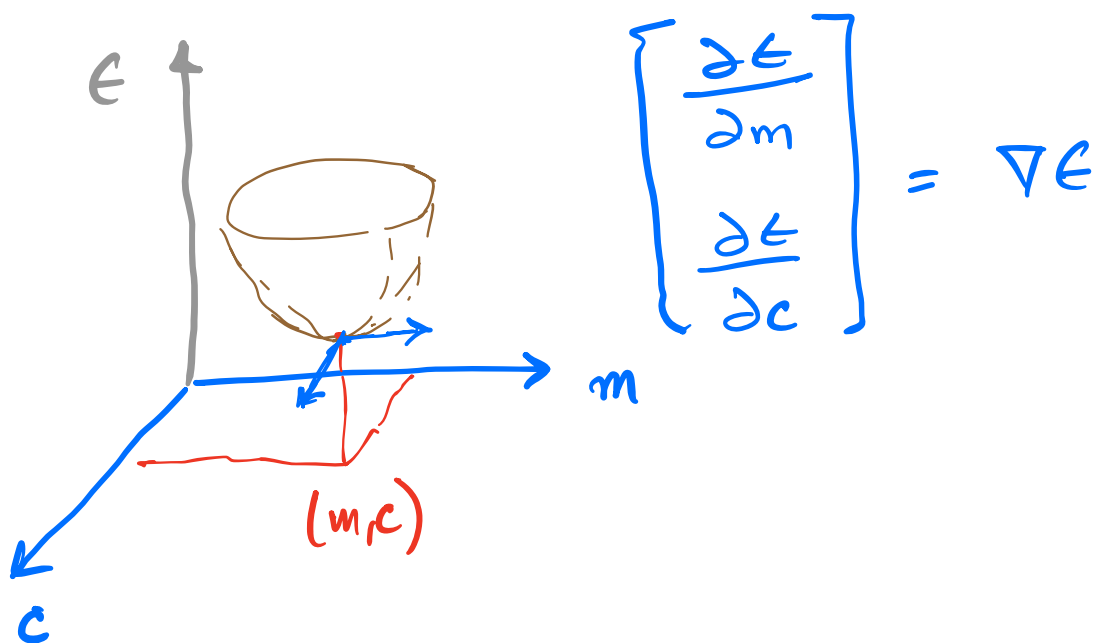
$$\epsilon = \frac{1}{n} \sum_{i=1}^n (y_i - (m x_i + c_i))^2$$

Ground truth

Model prediction

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$$m^*, c^* = \arg \min_{m, c} \epsilon$$



At location  $(m, c)$  where  $E$  is minimum,

$$\frac{\partial E}{\partial c} = 0 \quad \text{and} \quad \frac{\partial E}{\partial m} = 0$$


---

$$E = \frac{1}{n} \sum_{i=1}^n (y_i - mx_i - c)^2$$

$$\frac{\partial E}{\partial m} = \frac{1}{n} \sum_{i=1}^n -2x_i (y_i - mx_i - c)$$

$$\frac{\partial E}{\partial c} = \frac{1}{n} \sum_{i=1}^n -2(y_i - mx_i - c)$$

$$-\frac{2}{n} \sum_{i=1}^n x_i (y_i - mx_i - c) = 0 \quad \text{--- (2)}$$

$$-\frac{2}{n} \sum_{i=1}^n (y_i - mx_i - c) = 0 \quad \text{--- (1)}$$

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$$\frac{1}{n} \sum_{i=1}^n (y_i - mx_i - c) = 0$$

~~(1)~~

$$\Rightarrow \frac{1}{n} \sum_{i=1}^n y_i - \frac{m}{n} \sum_{i=1}^n x_i - \frac{1}{n} \sum_{i=1}^n c = 0$$

$$\Rightarrow \langle y \rangle - m \langle x \rangle - c = 0$$

(2)

---

$$\frac{1}{n} \sum_{i=1}^n x_i (y_i - mx_i - c) = 0$$

$$\Rightarrow \frac{1}{n} \sum_{i=1}^n x_i (y_i - mx_i - \langle y \rangle + m \langle x \rangle) = 0$$

$$\Rightarrow \frac{1}{n} \sum_{i=1}^n x_i (y_i - \langle y \rangle - m(x_i - \langle x \rangle)) = 0$$

$$\Rightarrow \frac{1}{n} \sum_{i=1}^n x_i (y_i - \langle y \rangle) - \frac{1}{n} \sum_{i=1}^n m x_i (x_i - \langle x \rangle) = 0$$

$$\Rightarrow m = \frac{\frac{1}{n} \sum_{i=1}^n x_i (y_i - \langle y \rangle)}{\frac{1}{n} \sum_{i=1}^n x_i (x_i - \langle x \rangle)}$$

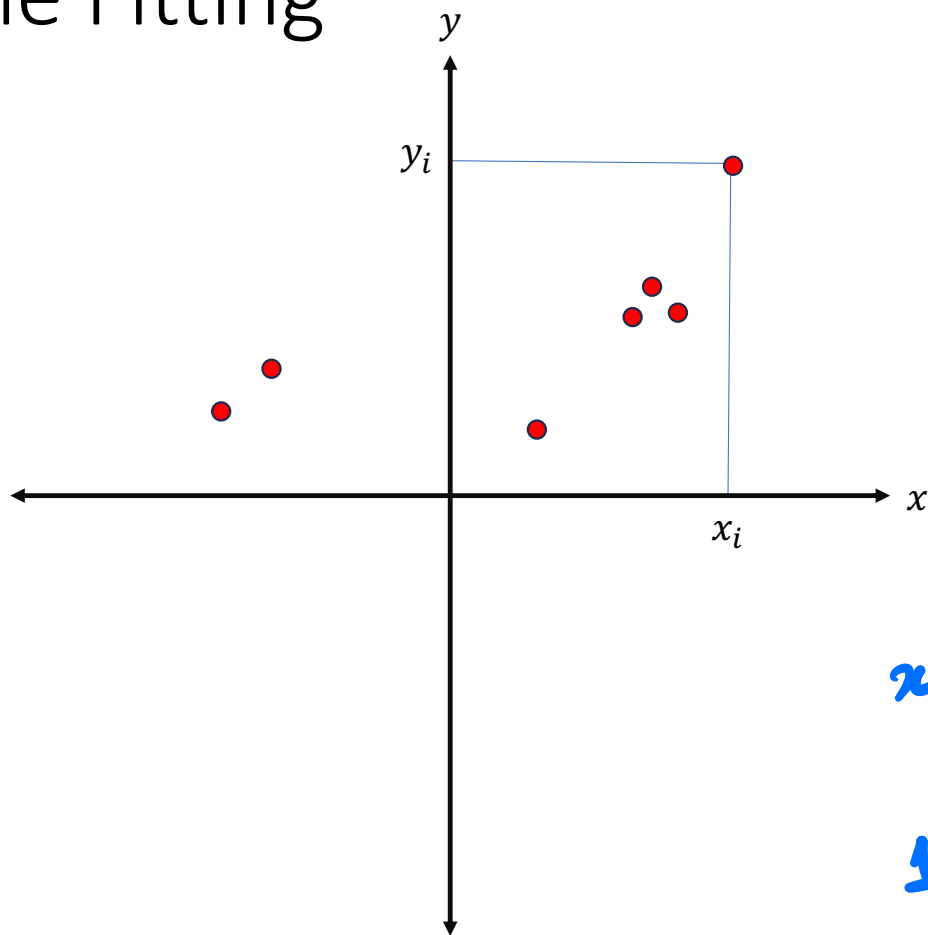
$$\Rightarrow m = \frac{\sum_{i=1}^n x_i (y_i - \langle y \rangle)}{\sum_{i=1}^n x_i (x_i - \langle x \rangle)}$$

→ Compute  $\underline{c}$ .

# Linear Regression

Going beyond 2D

# Line Fitting



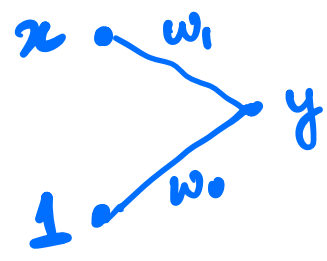
**1D features:  $x$**

**Ground truth:  $y$**

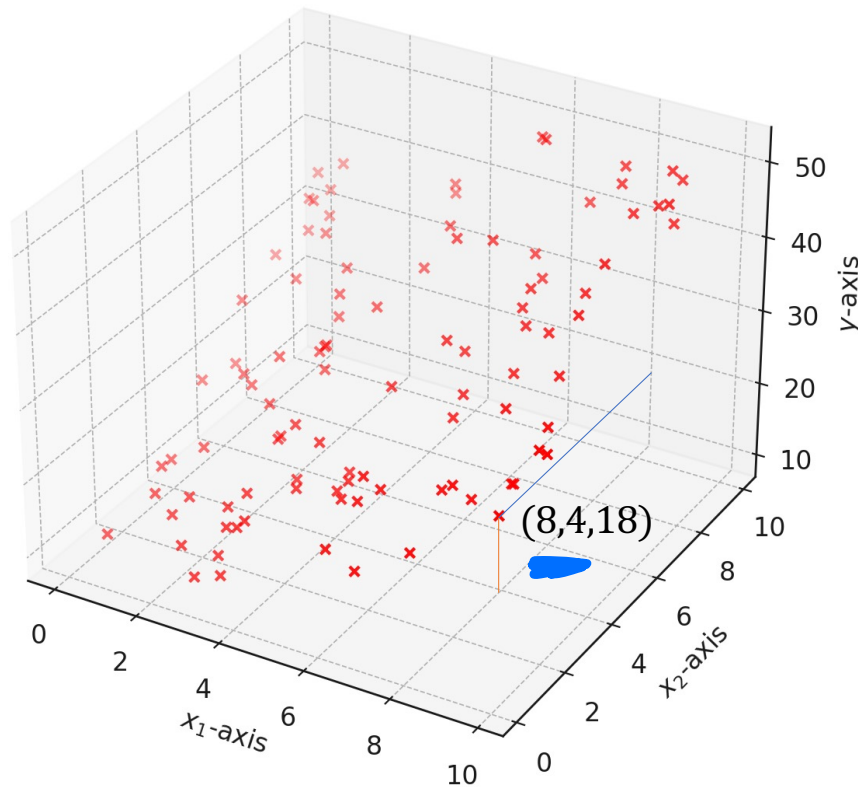
**Model**

$$y = mx + c \quad (\text{Line})$$

$$y = w_1x + w_0 \quad (\text{Re-write})$$



# 2D Features

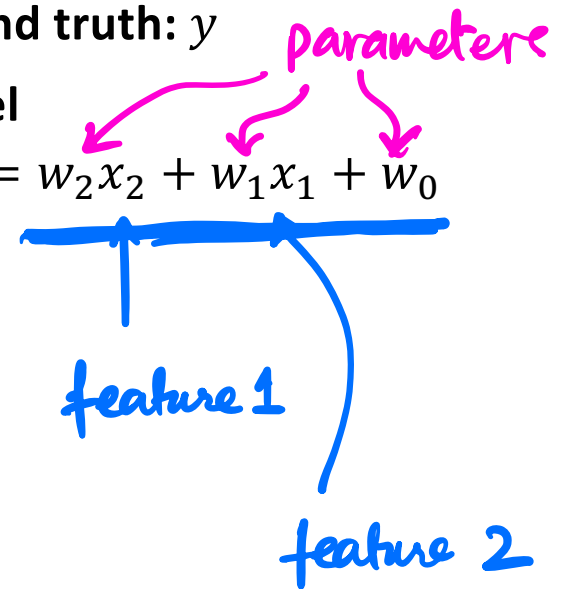


2D features:  $(x_1, x_2)$

Ground truth:  $y$

Model

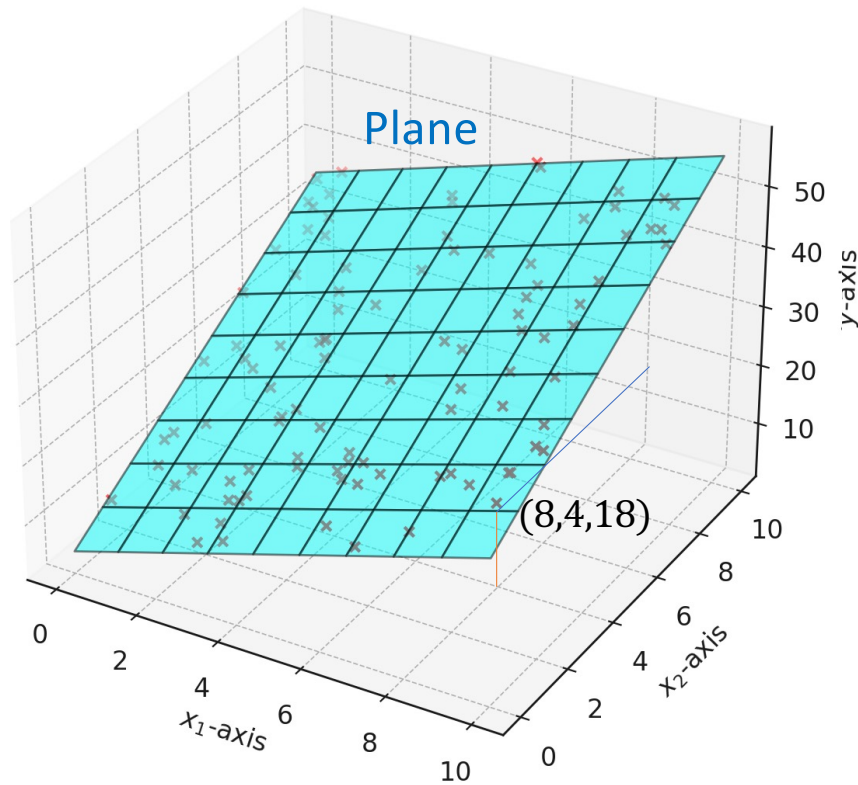
$$y = w_2x_2 + w_1x_1 + w_0$$



$$\epsilon_i = \left( y_i - (w_2x_{2i} + w_1x_{1i} + w_0) \right) \leftarrow \text{? vector form}$$

$$\epsilon = \frac{1}{n} \sum_i \epsilon_i$$

# 2D Features



**2D features:**  $(x_1, x_2)$

**Ground truth:**  $y$

**Model**

$$y = w_2x_2 + w_1x_1 + w_0$$



Features.

# Linear Models in Higher Dimensions

$$y = w_d x_d + \dots + w_2 x_2 + w_1 x_1 + w_0$$

↑ ↑ ↑ ↑

parameters.

→ =  $[w_d \quad \dots \quad w_2 \quad w_1 \quad w_0]$

$$\begin{bmatrix} x_d \\ \vdots \\ x_2 \\ x_1 \\ 1 \end{bmatrix}$$

not going to help us.

$$y_1 = [x_{d1} \quad \dots \quad x_{21} \quad x_{11} \quad 1] \begin{bmatrix} w_d \\ \vdots \\ w_2 \\ w_1 \\ w_0 \end{bmatrix}$$

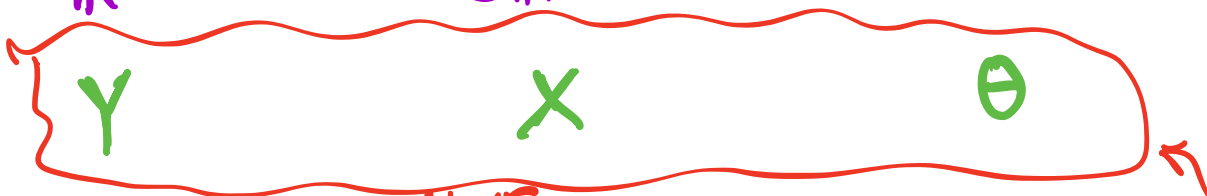
$$y_2 = [x_{d2} \quad \dots \quad x_{22} \quad x_{12} \quad 1]$$

ground truth

prediction

$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} x_{d1} & \dots & x_{21} & x_{11} & 1 \\ x_{d2} & \dots & x_{22} & x_{12} & 1 \\ \vdots & & \vdots & \vdots & \vdots \\ x_{dn} & \dots & x_{2n} & x_{1n} & 1 \end{bmatrix} \begin{bmatrix} w_d \\ \vdots \\ w_2 \\ w_1 \\ w_0 \end{bmatrix}$$

$\in \mathbb{R}^{n \times 1}$                        $\in \mathbb{R}^{n \times (d+1)}$                        $\in \mathbb{R}^{(d+1) \times 1}$



Model:

$$Y = X\theta$$

ground truth (pointing to Y)  
 predictions (pointing to Xθ)  
 Estimate (pointing to θ)

Error:

$$E = (X\theta - Y)^T (X\theta - Y)$$

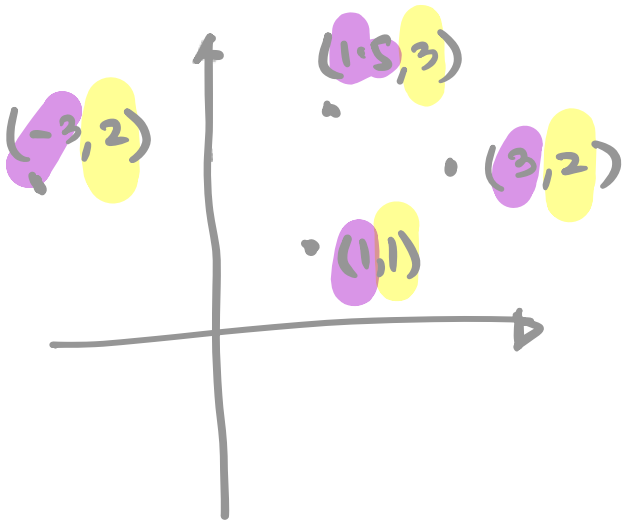
$$X\theta = w_d x_d + \dots + w_2 x_2 + w_1 x_1 + w_0$$

$$Y = y$$

$$(X\theta - Y) = (w_d x_d + \dots + w_2 x_2 + w_1 x_1 + w_0) -$$

$$(X\theta - y) = \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \vdots \\ \epsilon_n \end{bmatrix} \in \mathbb{R}^{n \times 1}$$

$$\begin{aligned} (X\theta - y)^T (X\theta - y) &= \epsilon_1^2 + \epsilon_2^2 + \dots + \epsilon_n^2 \\ &= \sum_{i=1}^n \epsilon_i^2 \end{aligned}$$



$$Y = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 2 \end{bmatrix}$$

$$X = \begin{bmatrix} 1 & 1 \\ 3 & 1 \\ 1.5 & 1 \\ -3 & 1 \end{bmatrix}$$

$$\theta = \begin{bmatrix} m \\ b \end{bmatrix}$$

$$X\theta = \begin{bmatrix} (1)(m) + (1)(b) \\ (3)(m) + (1)(b) \\ (1.5)(m) + (1)(b) \\ (-3)(m) + (1)(b) \end{bmatrix}$$

$$E = (X\theta - Y)^T (X\theta - Y)$$

→  $\frac{\partial E}{\partial \theta} = 0$  ; solve for  $\theta$

?

# Linear Models in Higher Dimensions

$$y = w_n x_n + \cdots + w_2 x_2 + w_1 x_1 + w_0$$

**2D line fitting is a special case**

$$y = \cancel{w_n x_n + \cdots + w_2 x_2} + w_1 x_1 + w_0$$

$$y = w_1 x_1 + w_0$$

$$y = mx + c$$

# Linear Regression

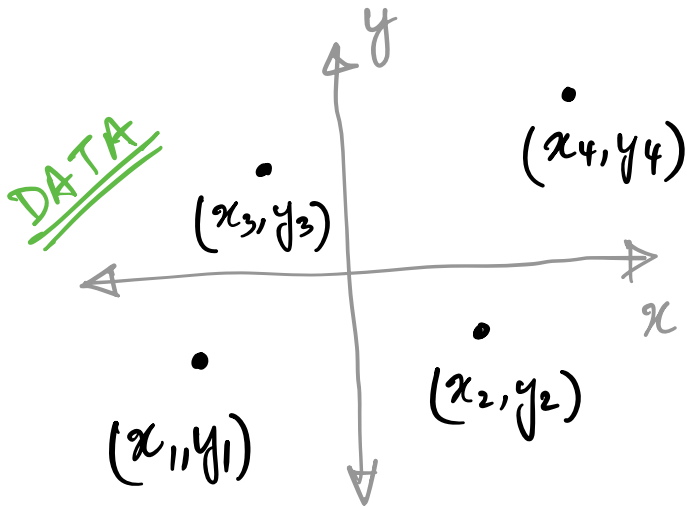
## Given

$(\vec{x}_1, y), (\vec{x}_2, y), \dots, (\vec{x}_n, y)$  where  $\vec{x}_i \in \mathbb{R}^d$

## Fit

$$y = w_d x_d + \dots + w_2 x_2 + w_1 x_1 + w_0$$

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Model

$$f: \mathbb{R} \rightarrow \mathbb{R}$$
$$: x \rightarrow y$$

$$y = mx + c$$
$$= \theta_1 x + \theta_0$$
$$= X \theta$$

↑  
design matrix

$$\theta = \begin{bmatrix} \theta_1 \\ \theta_0 \end{bmatrix}$$

$$\begin{bmatrix} \hat{y}_1 \\ \hat{y}_2 \\ \hat{y}_3 \\ \hat{y}_4 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \begin{bmatrix} \theta_1 \\ \theta_0 \end{bmatrix}$$

↑  
predictions ( $\hat{Y}$ )

Q. What is required to fit a model?

A. Minimize the fit error.  
loss

Example: MSE

$$L = \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2$$

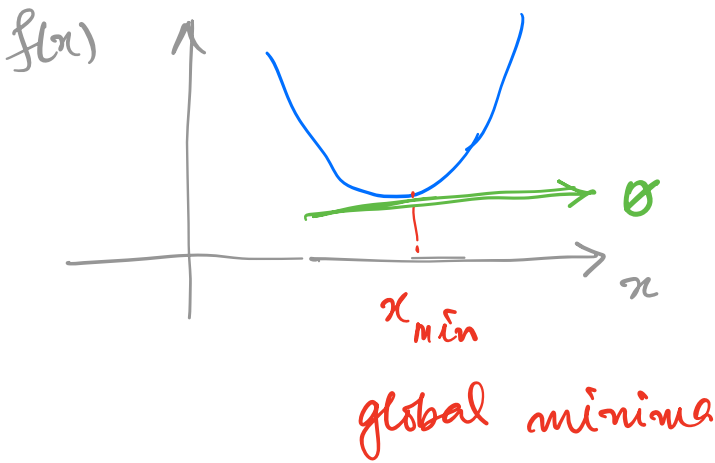
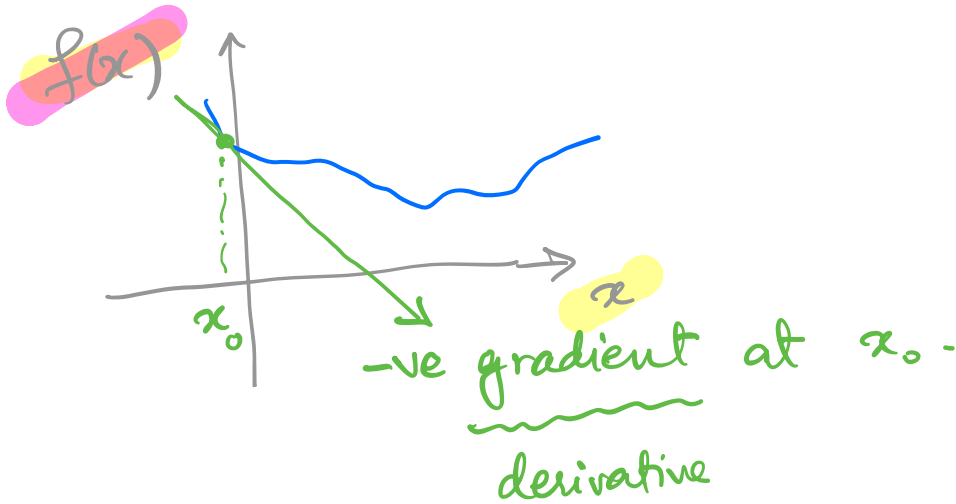
↑  
ground truth

Using  $\hat{y} = X\theta$ ,  $\rightarrow A\vec{x} = \vec{b}$   
 $\underline{X}\theta = \underline{Y}$

$$e = (Y - X\theta)^T (Y - X\theta)$$

$\downarrow$   
 predictions

Q. How do I minimize the error?



SOLVE

$$\nabla_{\theta} (Y - X\theta)^T (Y - X\theta)$$

$\uparrow$   $\uparrow$   
 parameters.

$$= \nabla_{\theta} Y^T Y - Y^T X\theta - (X\theta)^T Y + (X\theta)^T X\theta$$

$$= \nabla_{\theta} Y^T Y + \theta^T X^T X\theta - Y^T X\theta - (X\theta)^T Y$$



① real number.

②  $\text{tr } a = a, a \in \mathbb{R}$

$$= \nabla_{\theta} \text{tr} \left( \cancel{Y^T Y} + \theta^T X^T X \theta - Y^T X \theta - \underline{\underline{\theta^T X^T Y}} \right)$$

$$= \nabla_{\theta} \text{tr} \left( \theta^T X^T X \theta - \theta^T X^T Y - Y^T X \theta \right)$$

$$= \nabla_{\theta} \text{tr} \theta^T X^T X \theta - \nabla_{\theta} \text{tr} \theta^T X^T Y - \nabla_{\theta} \text{tr} Y^T X \theta$$

real number  
 $(\theta^T X^T Y)^T = \theta^T X^T Y$   
 $\Rightarrow Y^T X \theta$

$$= \nabla_{\theta} \text{tr} \theta^T X^T X \theta - \nabla_{\theta} \text{tr} Y^T X \theta - \nabla_{\theta} \text{tr} Y^T X \theta$$

$$= \nabla_{\theta} \text{tr} \theta^T X^T X \theta - 2 \nabla_{\theta} \text{tr} Y^T X \theta$$

---

②  $\nabla_A \text{tr } AB = B^T$

$\text{tr } AB = \text{tr } BA$

$\text{tr } ABC = \text{tr } CAB$

$$\textcircled{2} \quad \nabla_{\theta} \text{tr } Y^T X \theta$$

$$= \nabla_{\theta} \text{tr } \theta \underbrace{Y^T X}_{\substack{\text{A} \\ \text{B}}}$$

$$= (Y^T X)^T$$

$$= X^T Y$$


---

$$\nabla_A \text{tr } A B A^T C = C A B + C^T A B^T$$


---

$$\textcircled{1} \quad \nabla_{\theta} \text{tr } \theta^T X^T X \theta$$

$$= \nabla_{\theta} \text{tr } \theta \theta^T X^T X$$

$$= \nabla_{\theta} \text{tr } \theta \underbrace{I}_{\substack{\text{A} \\ \text{B} \\ \text{A}^T}} \theta^T \underbrace{X^T X}_{\text{C}}$$

$$= X^T X \theta I + (X^T X)^T \theta I^T$$

$$= X^T X \theta + \underbrace{(X^T X)^T}_{\text{square symmetric matrix}} \theta$$

square symmetric matrix

$$(X^T X)^T = X^T X$$

$$= X^T X \theta + X^T X \theta$$

$$= 2X^T X \theta$$

$$\nabla_{\theta} E = 2X^T X \theta - 2X^T Y$$

set it to 0

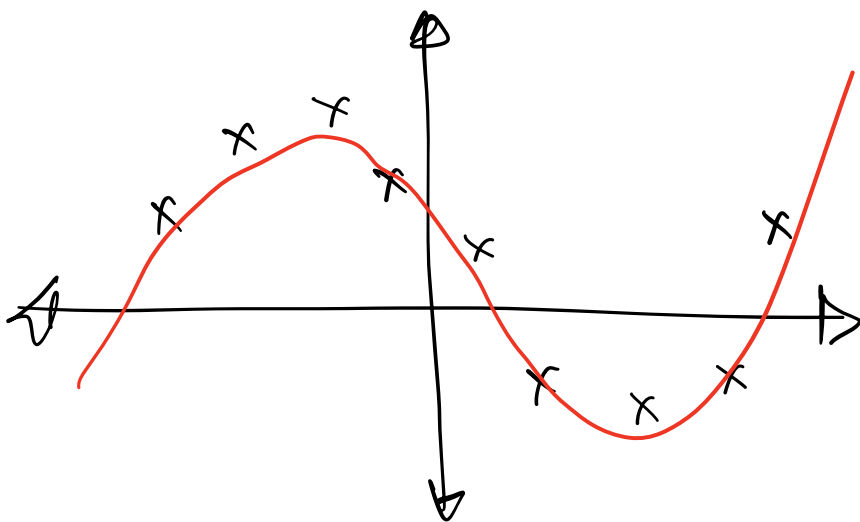
$$2X^T X \theta - 2X^T Y = 0$$

$$\Rightarrow X^T X \theta - X^T Y = 0$$

$$\Rightarrow X^T X \theta = X^T Y$$

$$\Rightarrow \theta = \underbrace{(X^T X)^{-1}}_{\text{pseudo-inverse}} X^T Y$$

Normal Equation.



$$y = x^3 w_3 + x^2 w_2 + x w_1 + w_0$$

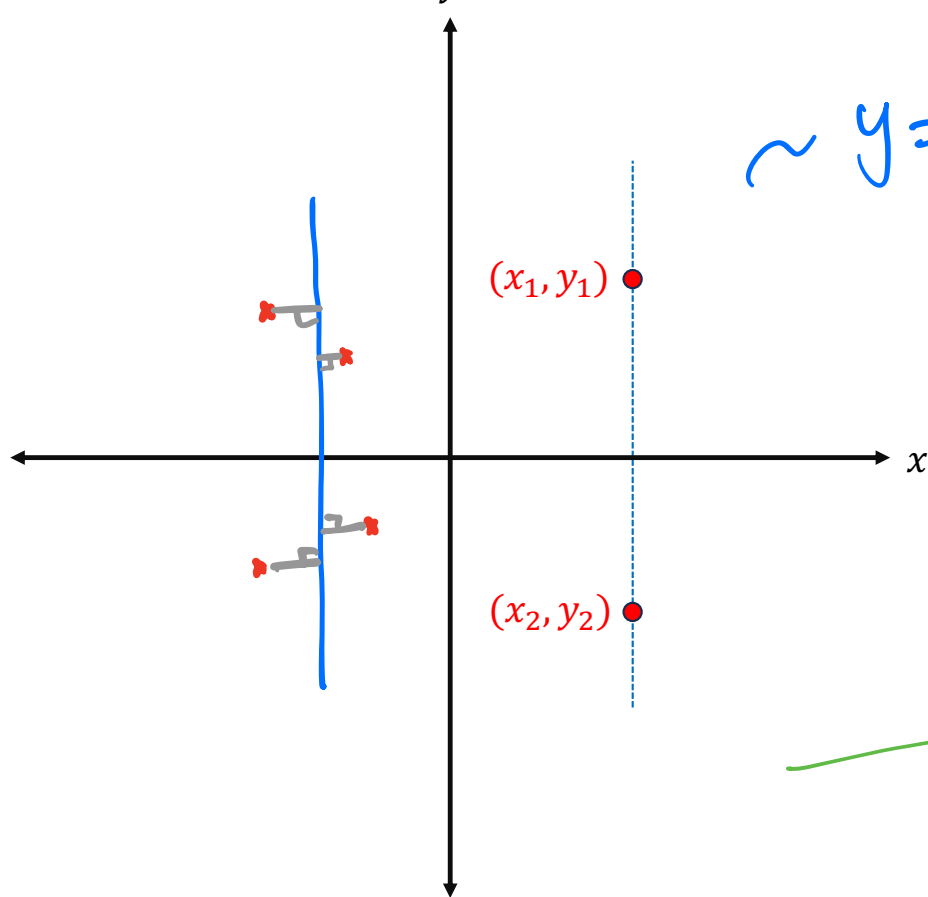
$$\text{tr} \begin{bmatrix} a & & & \\ & b & & \\ & & c & \\ & & & d \end{bmatrix} = a + b + c + d$$

*real number*

# Total least squares

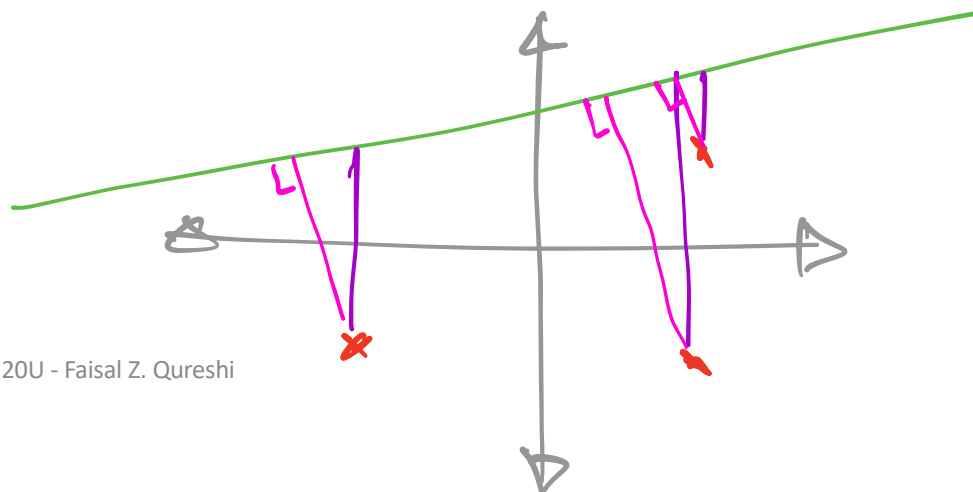
As opposed to ordinary least squares

# Back to Lines in 2D



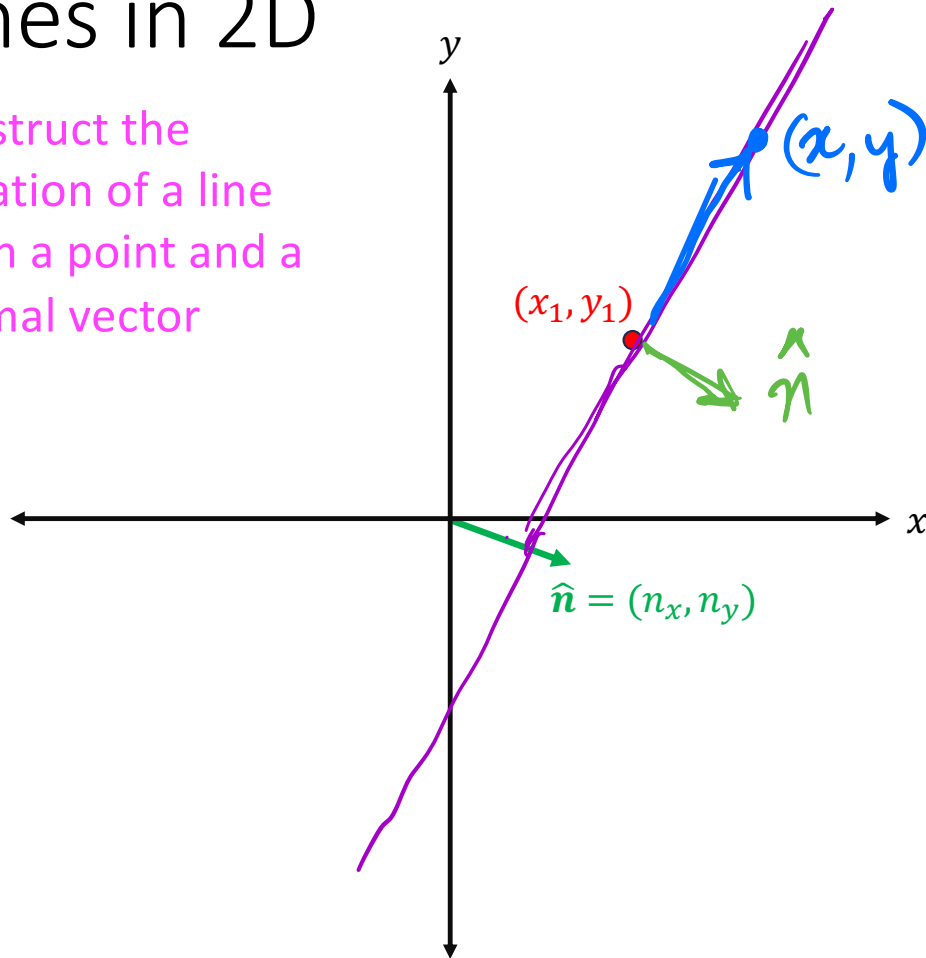
$$\sim y = mx + c$$

↓  
infinite (undefined)



# Lines in 2D

Construct the equation of a line given a point and a normal vector



$$A \vec{x} = \emptyset$$

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$$(x - x_1, y - y_1) \perp \hat{n}$$

$$(x - x_1, y - y_1) \cdot (n_x, n_y) = \emptyset$$

$$\Rightarrow (x - x_1)n_x + (y - y_1)n_y = \emptyset$$

$$\Rightarrow n_x x - x_1 n_x + n_y y - y_1 n_y = \emptyset$$

$$\Rightarrow \underbrace{n_x x}_a + \underbrace{n_y y}_b - \underbrace{x_1 n_x - y_1 n_y}_c = \emptyset$$

$$ax + by + c = \emptyset$$



# Total Least Squares vs Ordinary Least Squares

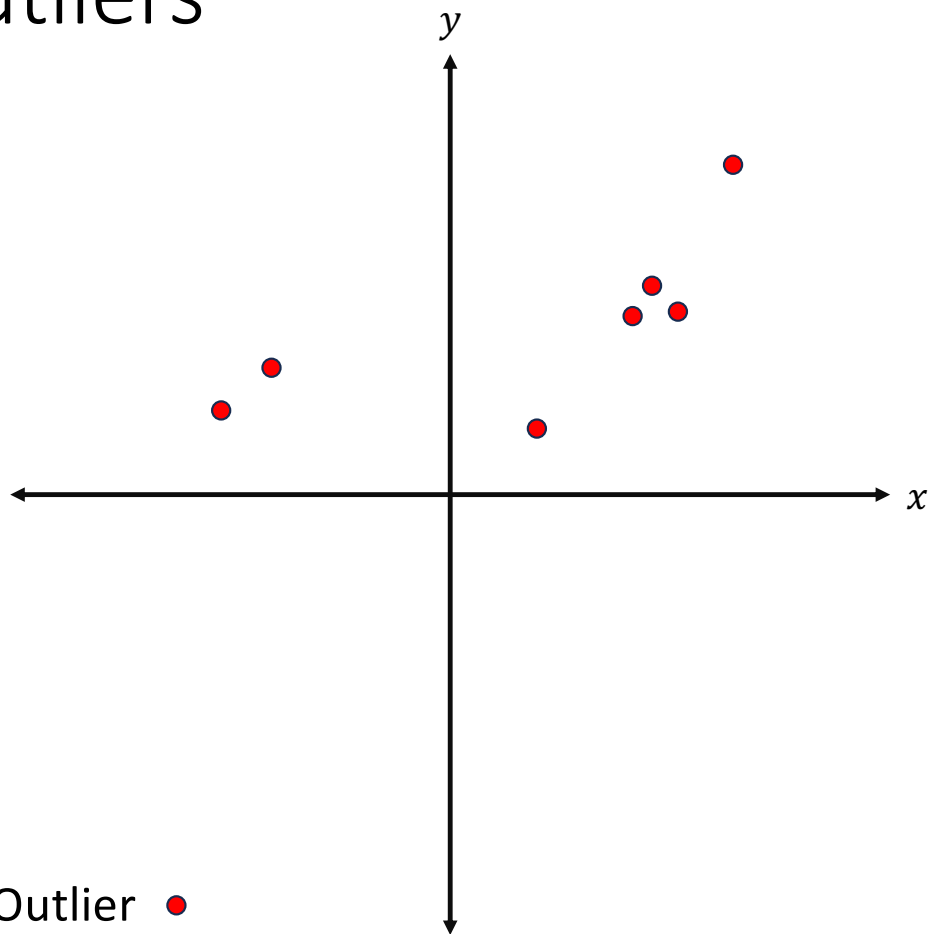
Method	Errors in $X$	Errors in $Y$	Distance minimized
Ordinary least squares	No	Yes	Vertical
Total least squares	Yes	Yes	Perpendicular



# Model fitting

Issues

# Outliers



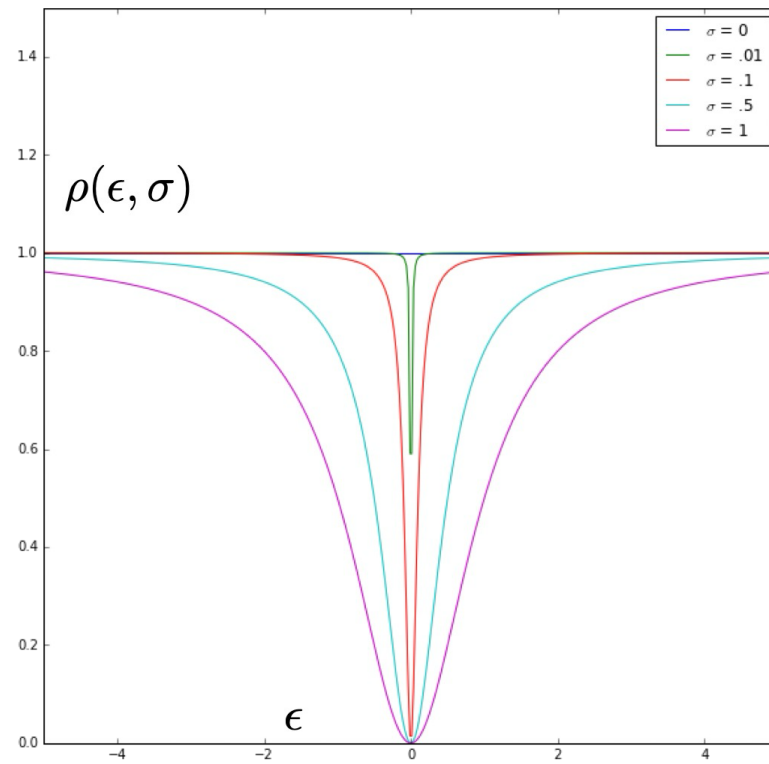
Least squares estimate is sensitive to outliers

Outlier ●

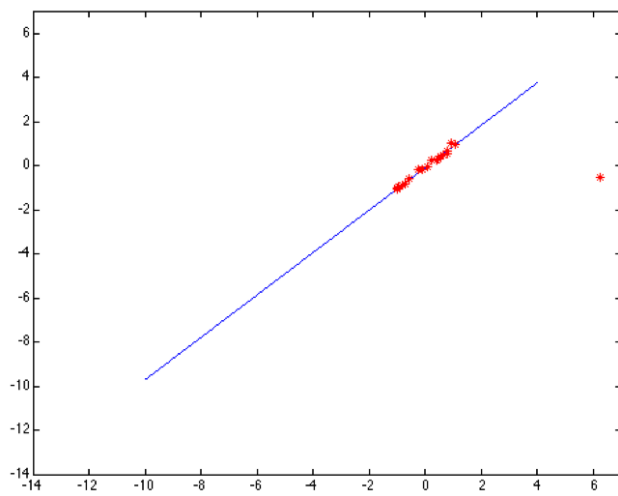
# Robust Least Squares

$$\rho(\epsilon, \sigma) = \frac{\epsilon^2}{\epsilon^2 + \sigma^2}$$

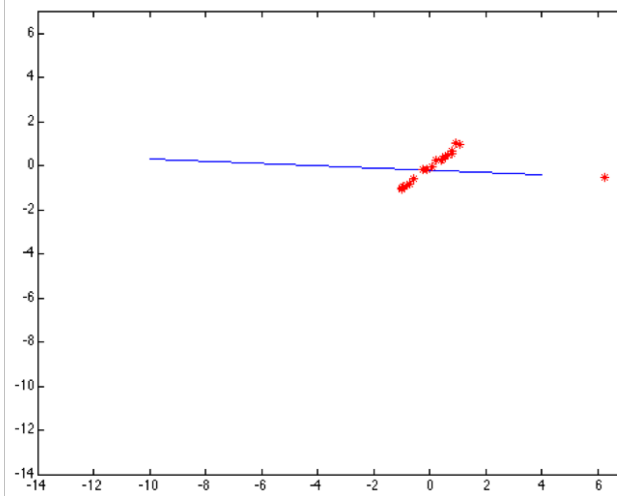
↑  
Scale parameter



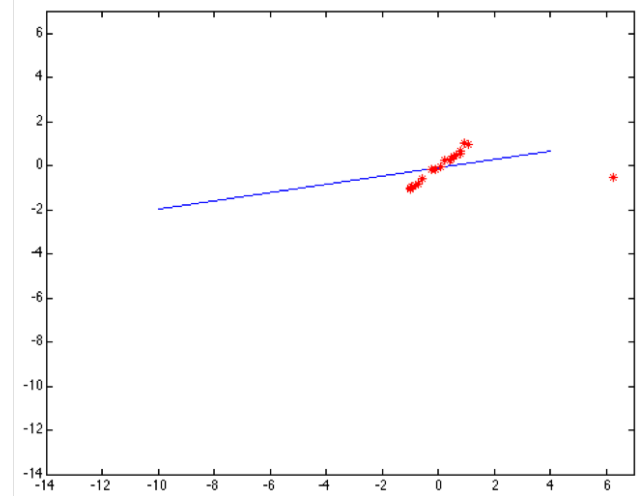
# Robust Least Squares



When scale is just right, the effects of outliers are eliminated

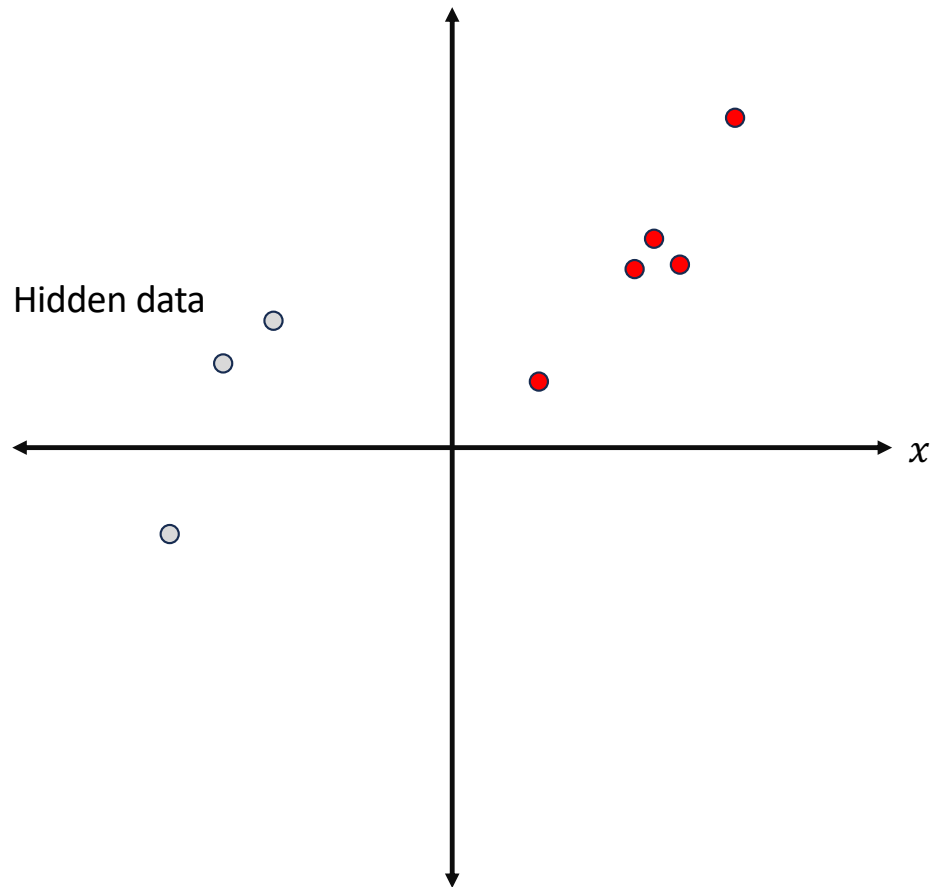


When scale is too small, the error value for almost all points is the same. This results in a poor fit.



When scale is too large, the system behaves like good old least squares, i.e., it remains sensitive to outliers.

# Incomplete data



## Hidden data

Not available at the time of model fitting

# Summary

- Line fitting in 2D
- Least squares
- How to deal with outliers?

Minimizing  $\epsilon = \sum_{i=1}^n (y_i - (m x_i + c_i))^2$

Re-write  $\epsilon = \sum_{i=1}^n (y_i - (m x_i + c_i))^2$  in Matrix Form



