

High Dynamic Range Photography

Computational Photography (CSCI 3240U)

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High Dynamic Range (HDR) Photography

- Human eyes have high visual range
 - It can differentiate and see structure between very bright and very dark regions in a scene
- An image is taken at a particular exposure setting, which determines whether it contains more visible structure in brighter or darker regions



Images taken at various exposure settings

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HDR techniques combine multiple images of the same scene to emulate the high visual range of human eyes

Images taken at various exposure settings

High Dynamic Range (HDR) Photography



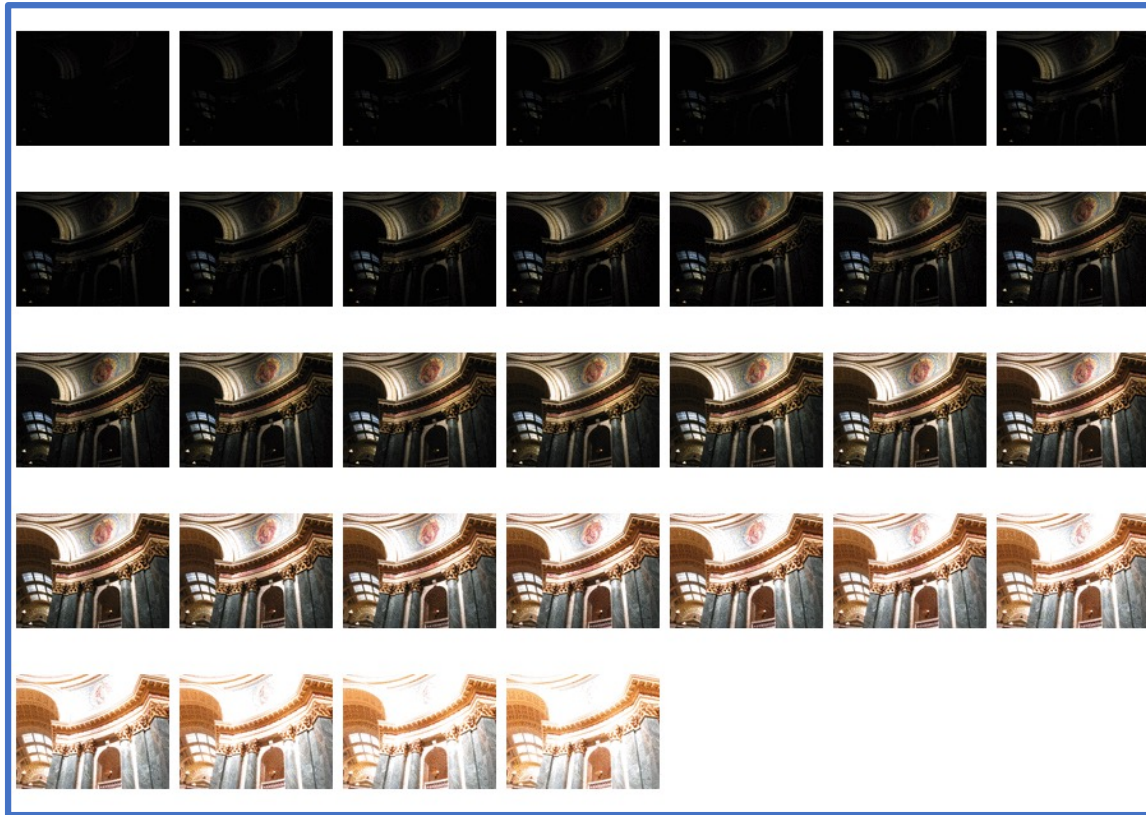
Images taken at various exposure settings

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HDR image

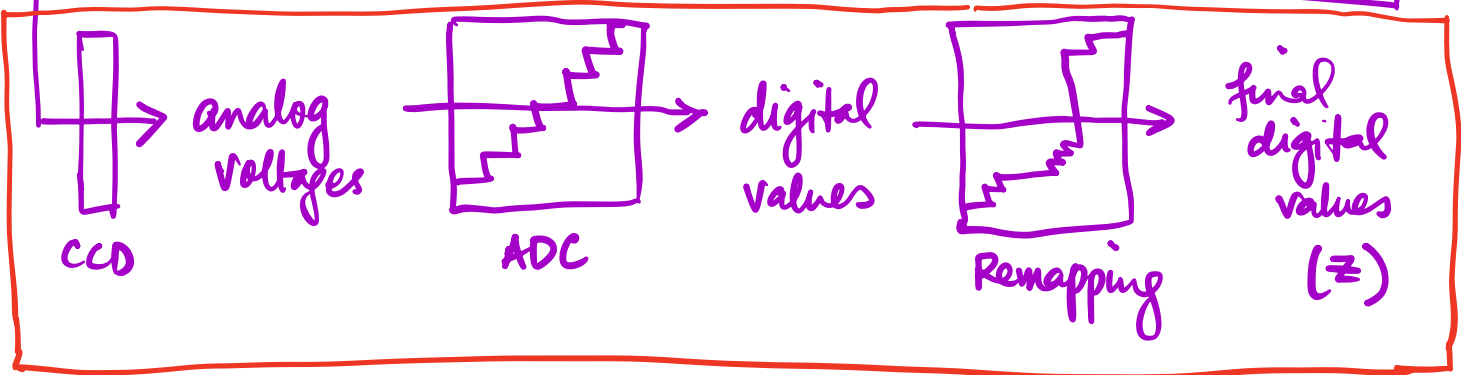
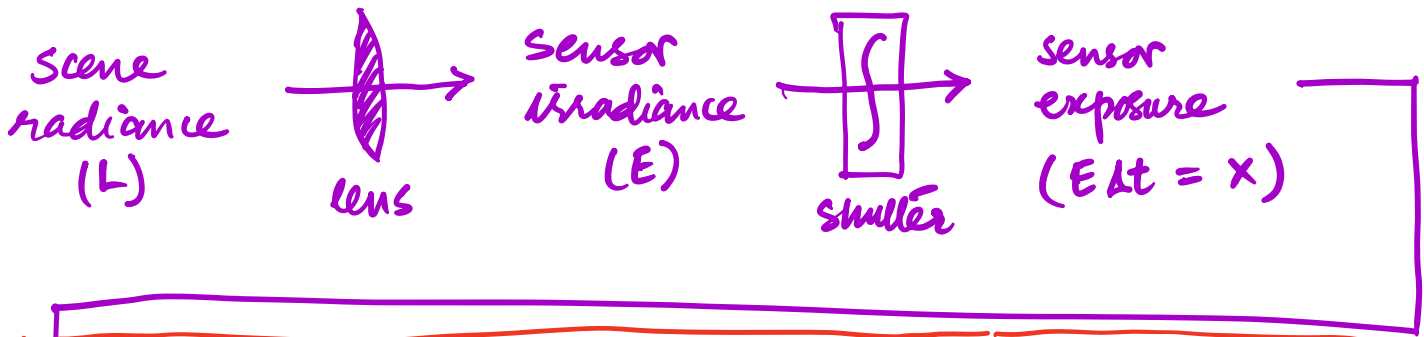
High Dynamic Range (HDR) Photography



Images taken at various exposure settings



HDR image



$$Z = f(E \Delta t)$$

observed pixels → Z

camera response function → f

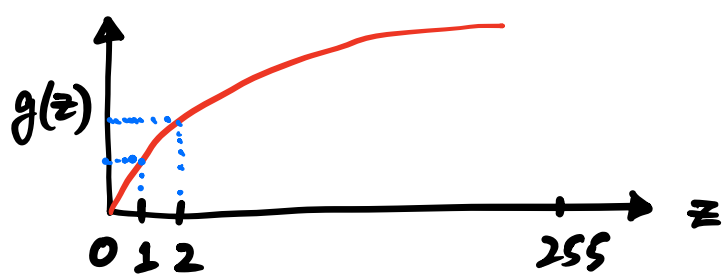
Goal: Compute the camera response function (f).

$$z = f(E \Delta t)$$

$$f^{-1}(z) = E \Delta t$$

$$\log f^{-1}(z) = \log E + \log \Delta t$$

$$g(z) = \log E + \log \Delta t \quad \text{--- (1)}$$

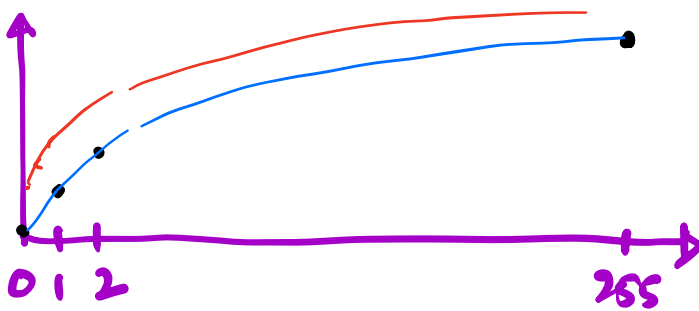
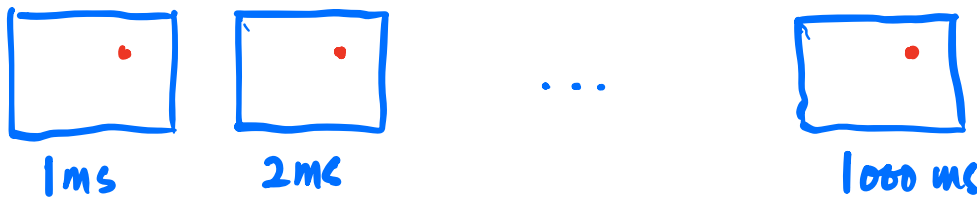


We need to compute $g(z)$: $g(0), g(1), g(2), \dots, g(255)$.

256 values

Approach 1

- One pixel and many many images
- Images are taken by finely adjusting Δt
- Plot $\log \Delta t$ as a function of pixel intensity.



Drawbacks: need to acquire too many images.
how to control Δt to hit all possible
 z values between 0 and 255.
what if you store 16-bit pixels. Here
possible values are between 0 and $2^{16}-1$.
Does not scale!!

What happens $\log E$?

$$g(z) = \boxed{\log E} + \log \Delta t$$

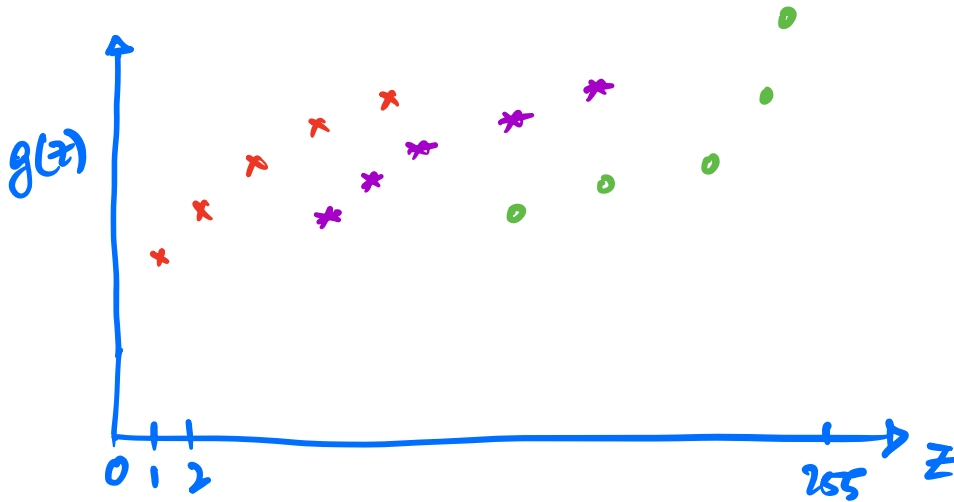
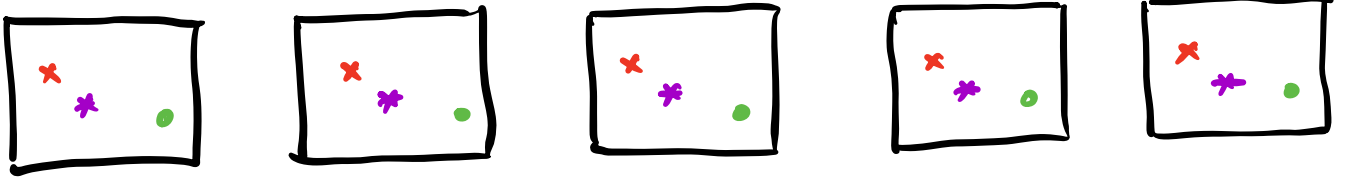
↑
same value for all the
images

Simplified

$$\rightsquigarrow g(z) \approx \log \Delta t$$

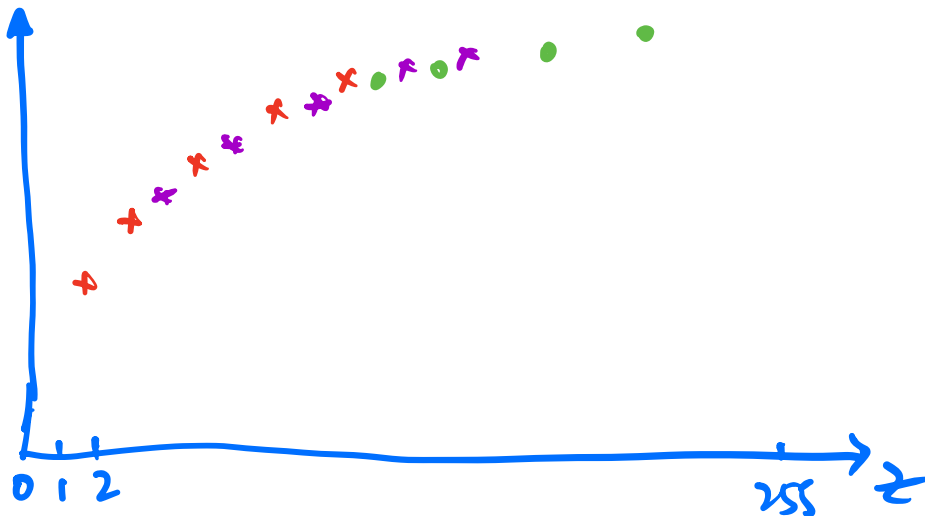
Approach 2

- Few pixels and a few images.



Plot of $g(z)$
from three
images.

Computed $g(z)$



Benefit over approach 1:

we need far far fewer images.

Approach 2 (mathematics).

N pixels
 P images.

Example:

$N=3$
 $P=5$

$$g(z_{ij}) = \log E_i + \log \Delta t_j \quad \text{--- } \textcircled{2}$$

i^{th} pixel
in j^{th} image

irradiance
for i^{th}
pixel

exposure
interval of
 j^{th} image.

Unknowns: $g(0), \dots, g(255)$ [256] $z_{ij} \in [0, 255]$
 E_i [N]

Given Δt_j

of unknowns = 256 + N

of equations = NP

Simplified notation:

$$g(z_{ij}) = g_{ij}$$

$$\log E_i = e_i$$

$$\log \Delta t_j = \delta_j$$

Re-write $\textcircled{2}$

$$g_{ij} = e_i + \delta_j$$

$$\Rightarrow g_{ij} - e_i = \delta_j \quad \text{--- (3)}$$

I want to express this as $Ax = b$

$$x = \begin{bmatrix} g_0 \\ g_1 \\ \vdots \\ g_{255} \\ e_1 \\ \vdots \\ e_N \end{bmatrix} \in \mathbb{R}^{(256+N) \times 1}$$

$$\begin{aligned} g_0 &= g(0) \\ &\vdots \\ g_{255} &= g(255) \end{aligned}$$

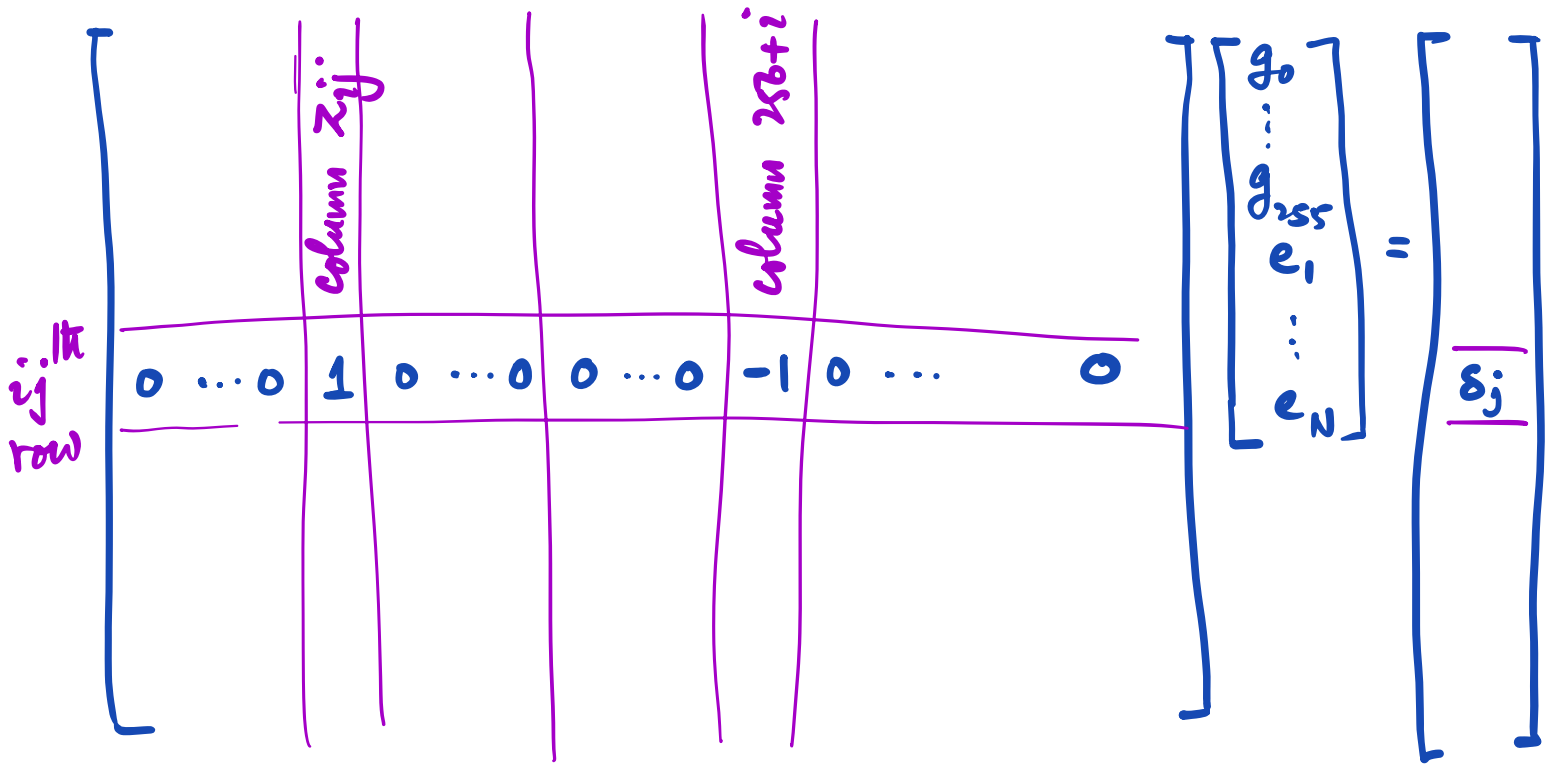
Express (3) as $Ax = b$

$$\begin{bmatrix} 0 & \dots & 0 & 1 & 0 & \dots & 0 & 0 & \dots & 0 & -1 & 0 & \dots & 0 \end{bmatrix} \begin{bmatrix} g_0 \\ g_1 \\ \vdots \\ g_{255} \\ e_1 \\ \vdots \\ e_N \end{bmatrix} = [\delta_j]$$

z_{ij}^{th} column
column

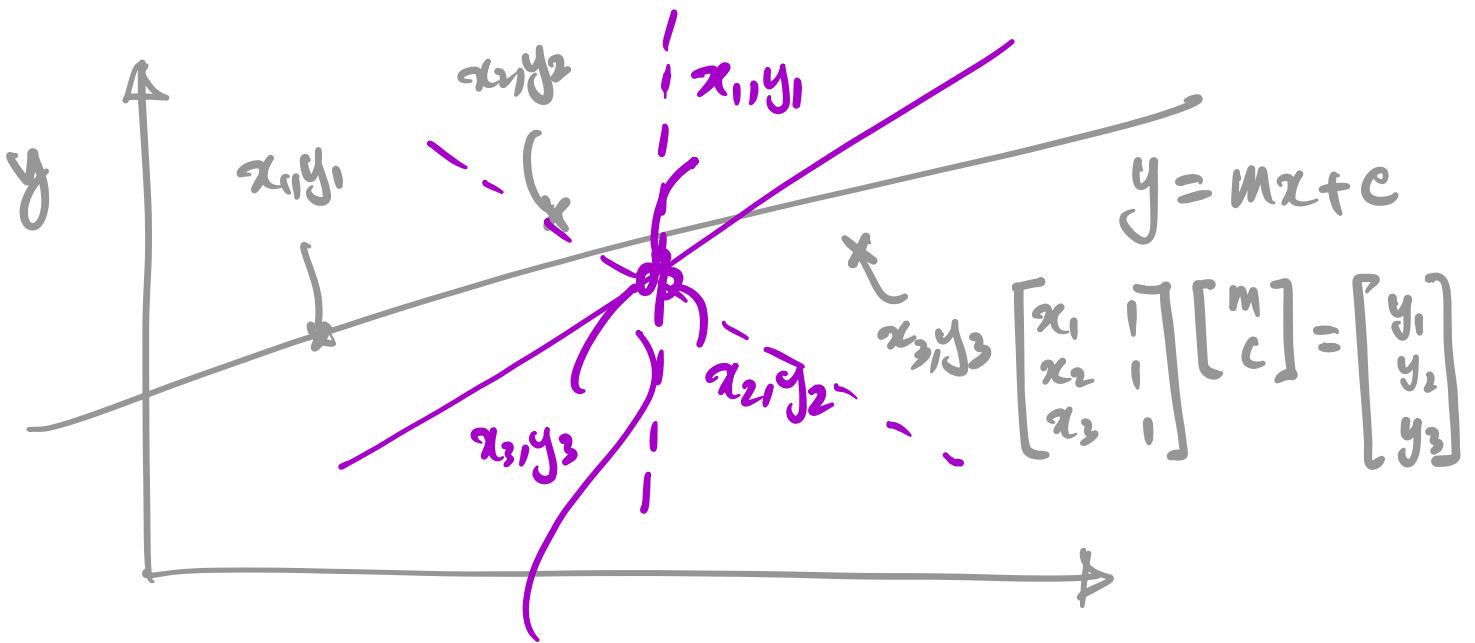
co-efficients of $g_0 \dots g_{255}$

co-efficients of $e_1 \dots e_N$



$$A \in \mathbb{R}^{NP \times (256+N)}$$

$$x \in \mathbb{R}^{256+N} = b \in \mathbb{R}^{NP}$$



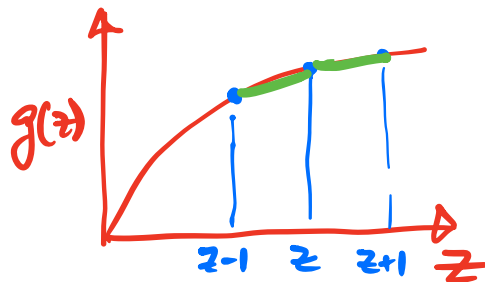
$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \begin{bmatrix} m \\ c \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$$

$$\begin{bmatrix} x_1 & 1 \\ x_2 & 1 \\ x_3 & 1 \end{bmatrix} \begin{bmatrix} m \\ c \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \quad x$$

Consider $Ax = b$. What if A is ill-conditioned?
 How do we address this issue?

→ "regularize"

Real camera response curves (functions) varies smoothly.



Add more equations to enforce smoothness

$$g(z) - g(z-1) = g(z+1) - g(z) \quad *$$

Re-write this as

$$2g(z) - g(z-1) - g(z+1) = 0$$

$$\begin{array}{ccccccc}
 [& 0 & \dots & 0 & -1 & 2 & -1 & 0 & \dots & 0 &] & \begin{array}{c} g_0 \\ g_1 \\ \vdots \\ g_{z-1} \\ g_z \\ g_{z+1} \\ \vdots \\ g_{255} \end{array} & = & [0]
 \end{array}$$

z column $z+1$ column $z+2$ column

For a particular g_z, g_{z-1}, g_{z+1}

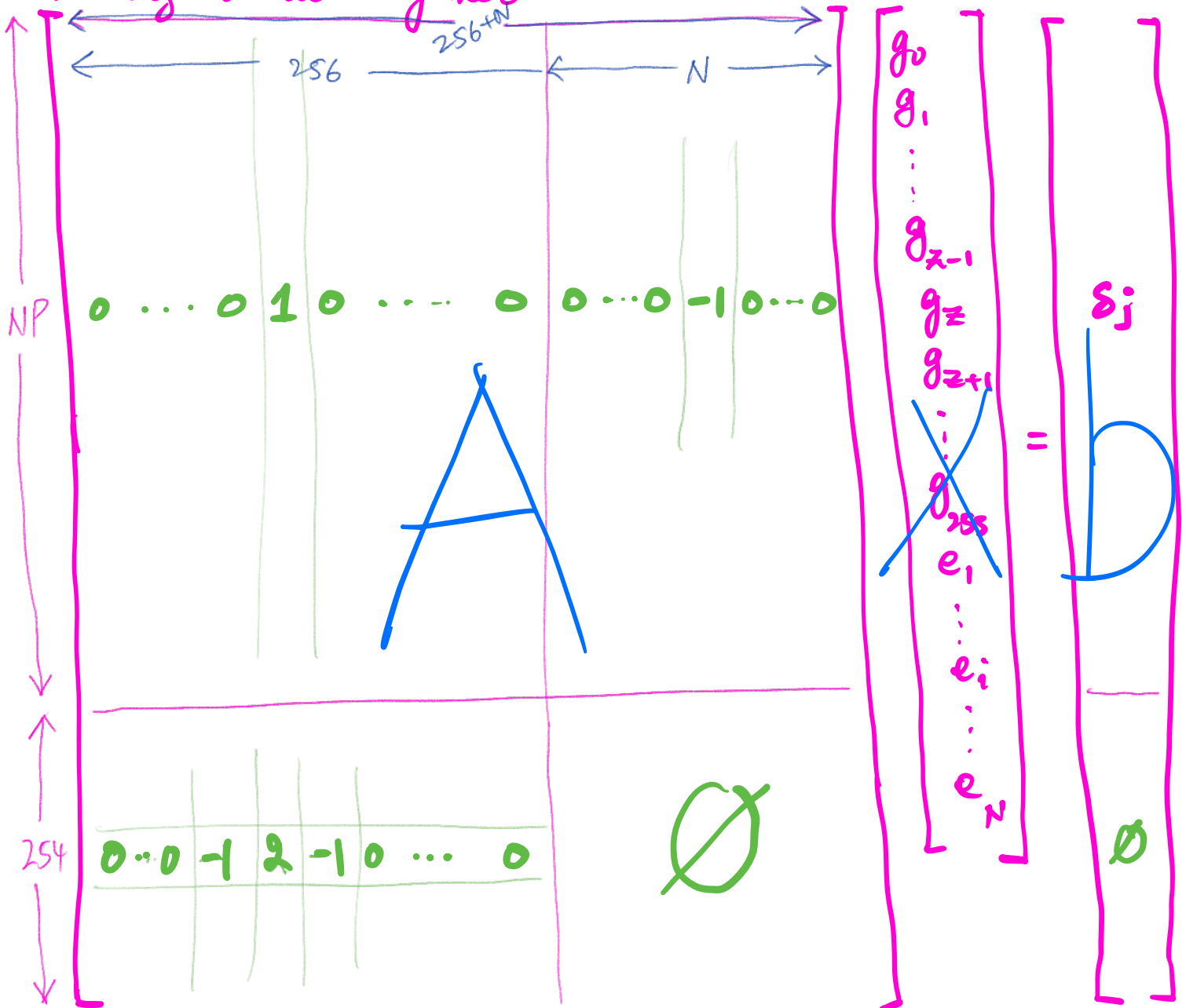
We have g_0, \dots, g_{255} . We extend the idea to all possible values of $z \in [0, 255]$.

We get 254 more equations:

$$\begin{aligned}
 2g_1 - g_0 - g_2 &= 0 \\
 2g_2 - g_1 - g_3 &= 0 \\
 &\vdots \\
 2g_{254} - g_{253} - g_{255} &= 0
 \end{aligned}$$

\updownarrow
 254

Putting it all together:



$$g(z) = \log E + \log \Delta t$$

$$\Rightarrow \log E = g(z) - \log \Delta t.$$

↑
irradiance of that pixel.

shutter speed

while $z \in [0, 255]$, $E \in [0, \infty]$ (HDR)

Process of compressing
a range to the
available range.

tone-mapping

because
irradiance can not be
displayed on a standard
display.

For HDR logarithmic tone-mapping:

- Given an image I .
- $I' = \log(1 + \alpha I) / \log(1 + \alpha)$
 - $\alpha = 0.1$, controls the strength of tone-mapping.
smaller results in stronger compression.
- $I'' = [I' - \min(I')] / [\max(I') - \min(I')]$
 - remapping pixel values between 0 and 1.
- $R = (I'' \times 255.0) \rightarrow \text{int8}$
 - ↑
result.

High Dynamic Range (HDR) Photography

- Collect images at different exposure settings
 - Align images if needed
- Estimate response curve
 - Set up the system of linear equations and solve for unknowns
- Use response curve to compute pixel irradiance values
- Perform tone mapping to construct the final HDR image that can be displayed on a device with limited dynamic range

Reference

- https://pages.cs.wisc.edu/~csverma/CS766_09/HDRI/hdr