

# Optimizations

CSCI 2050U - Computer Architecture

Randy J. Fortier  
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# Outline

- Optimizations
  - Pipelining
  - Hyperthreading

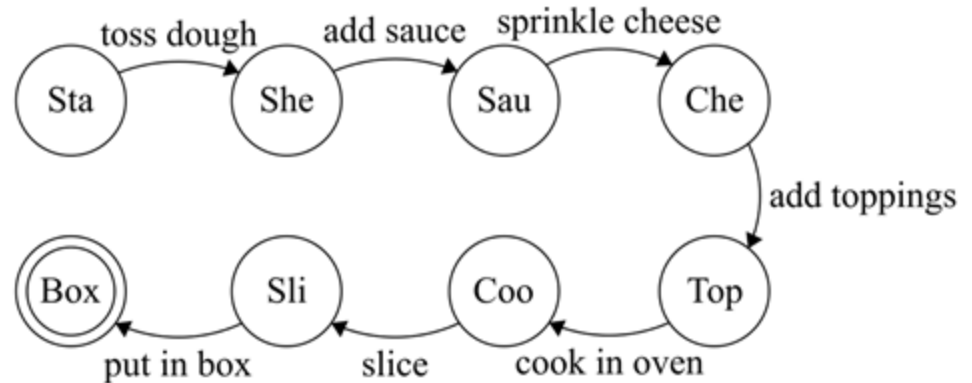
# Optimizations

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# Pipelining

- Imagine you work at a pizza place, making pizzas:
  - Toss the dough
  - Add sauce
  - Sprinkle cheese
  - Add toppings
  - Cook in oven
  - Slice
  - Box
- When not busy, you might:



# Pipelining

- What if it is busy?

# Pipelining

- What if it is busy?
  - The pizza takes a long time to cook in the oven, and you can't really do anything useful (e.g. slice) that pizza until it has finished cooking
  - Parallelism - while the first pizza is in the oven, you can start the second pizza

# Pipelining

- What if it is busy?
  - The pizza takes a long time to cook in the oven, and you can't really do anything useful (e.g. slice) that pizza until it has finished cooking
  - Parallelism - while the first pizza is in the oven, you can start the second pizza
- This is quite similar to executing instructions in a CPU
  - Fetch the instruction and operand values
  - Decode the instruction
  - Execute the instruction

# Pipelining

- Without pipelining
  - Fetch the opcode and operand values for the first instruction

Fetch

Decode

Execute



# Pipelining

- Without pipelining
  - Fetch the opcode and operand values for the first instruction
  - Decode the first instruction



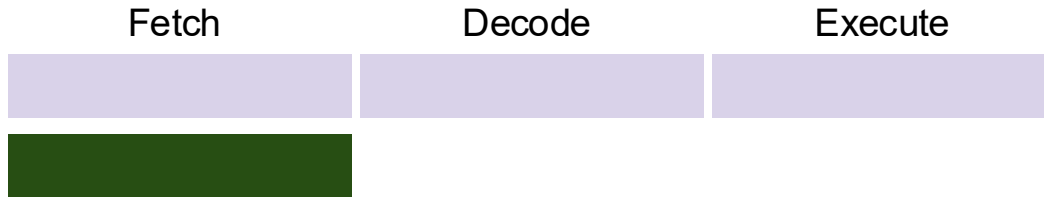
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  - Execute the first instruction
  - Fetch the opcode and operand values for the second instruction



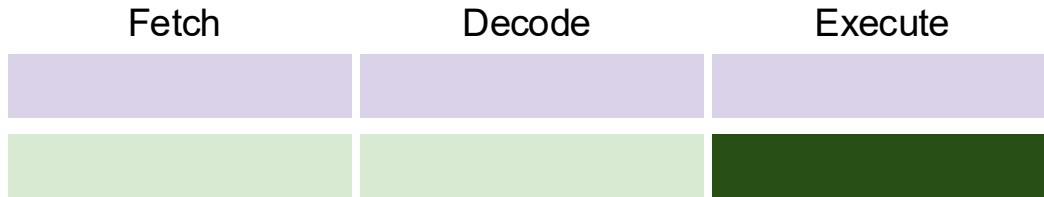
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- Without pipelining
  - Fetch the opcode and operand values for the first instruction
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  - Fetch the opcode and operand values for the second instruction
  - etc.



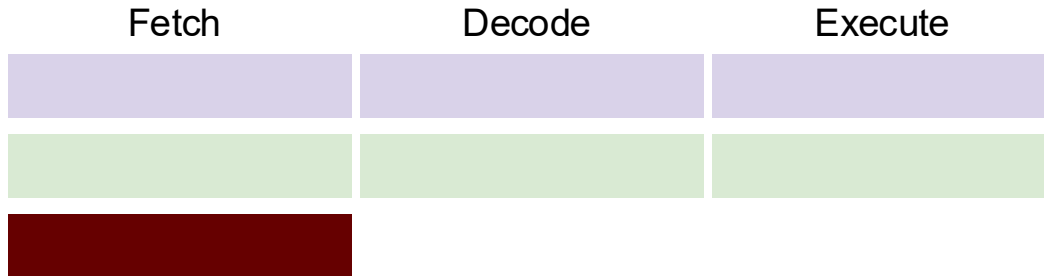
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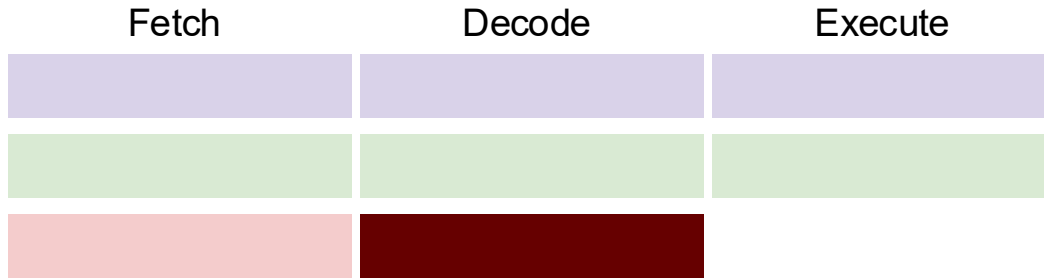
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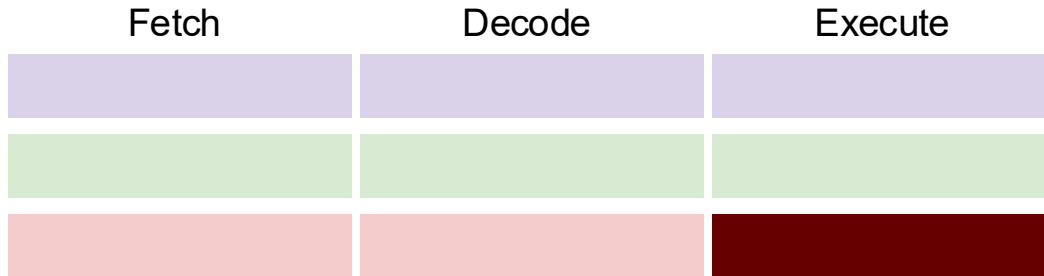
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# Pipelining

- Pipelining in action
  - Fetch the opcode and operand values for the first instruction

Fetch

Decode

Execute



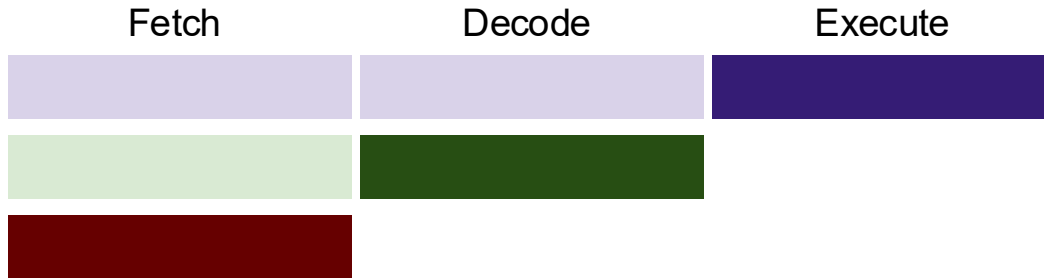
# Pipelining

- Pipelining in action
  - Fetch the opcode and operand values for the first instruction
  - Decode the first instruction, and fetch the second



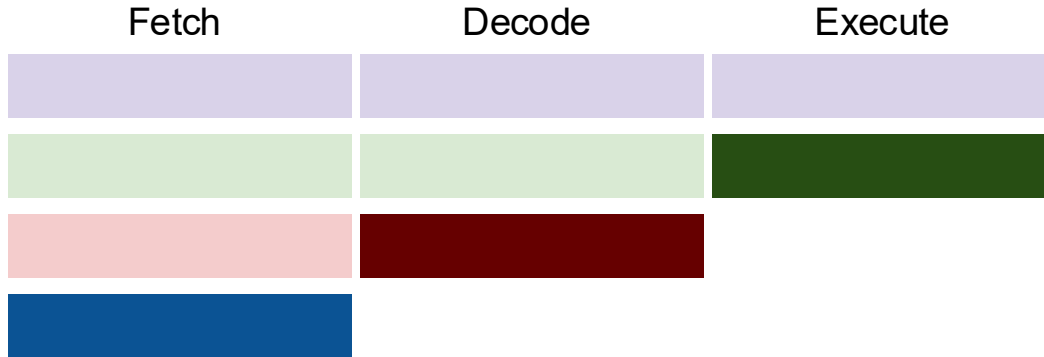
# Pipelining

- Pipelining in action
  - Fetch the opcode and operand values for the first instruction
  - Decode the first instruction, and fetch the second
  - Execute the first, decode the second, and fetch the third



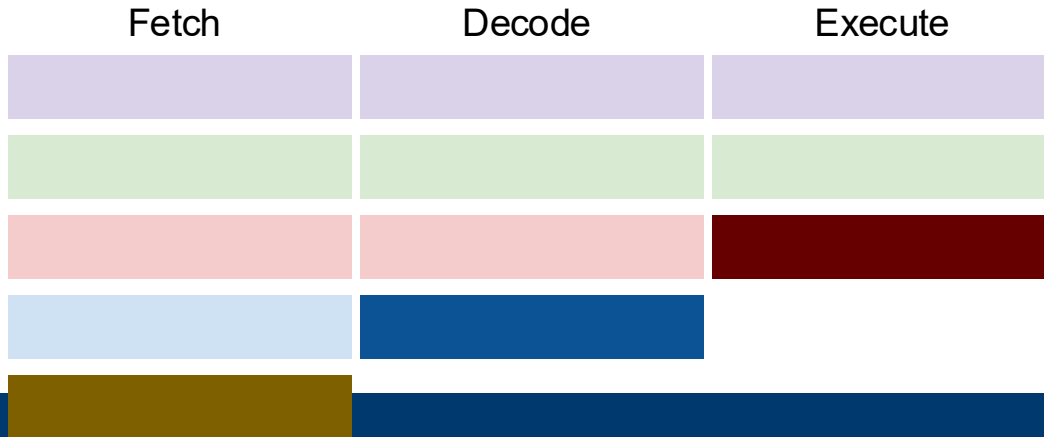
# Pipelining

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  - etc.



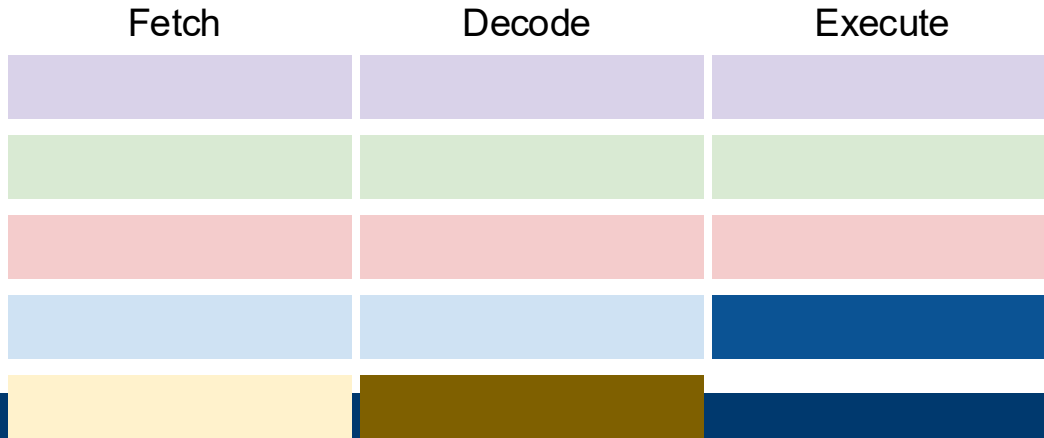
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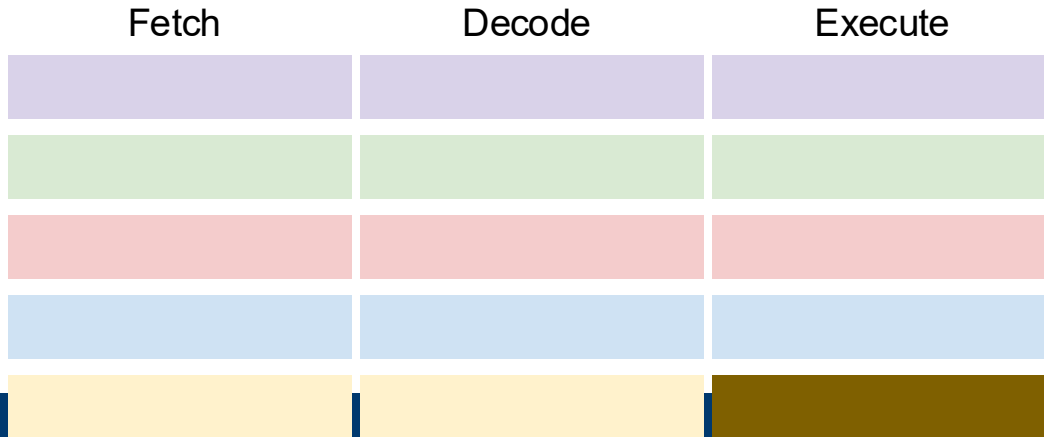
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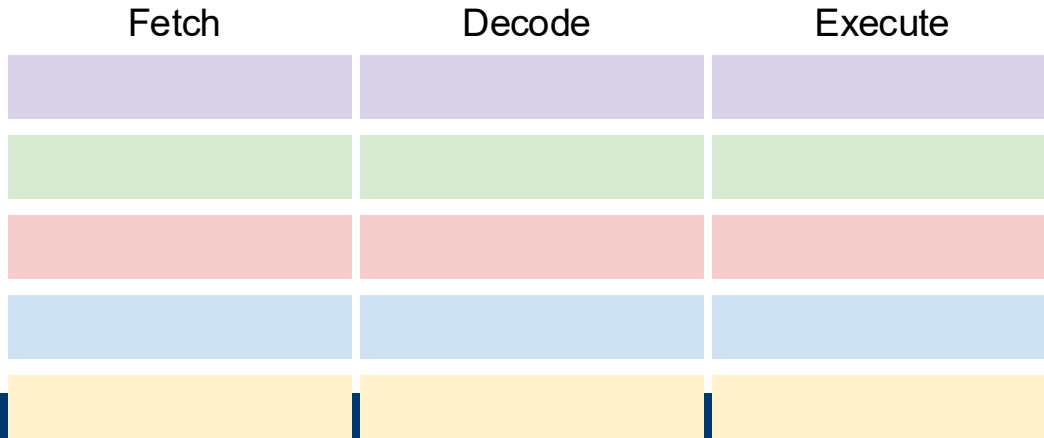
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  - Fetch the opcode and operand values for the first instruction
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  - etc.



# Pipelining

- But...
  - Pipelining breaks down on branch/jump instructions
  - Pipelining may break down if a subsequent instruction requires the values from a previous instruction

# Pipelining

- Branch prediction
  - The CPU guesses which path the program will take, and pre-executes the instructions along that execution path
    - e.g. If a branch has been true for the past 10 iterations of the loop, let's assume it will be true again this time
  - If it guesses wrong, it may need to undo everything it has done since the branch
    - This may be worth it if the predictions are accurate enough

# Multi-core CPUs and GPUs

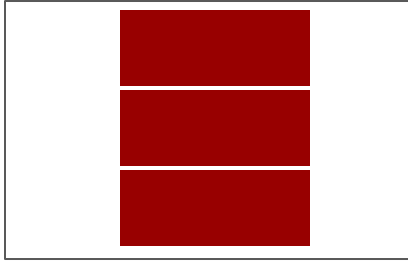
- Multi-core CPUs have become the standard for most devices
  - These are CPUs with multiple physical processing units
    - Multiple ALUs, multiple control units, multiple register sets
  - GPUs are similar, except they have far more numerous, but simpler, cores
- These multi-core systems will be examined further in a future course (CSCI 4060U - Massively Parallel Programming)

# Hyper-threading

- As we've seen, adjacent instructions are often dependent
  - Instruction A modifies a value used by instruction B
  - It may not be possible for pipelining to pre-execute instruction B, since the values it needs are not yet ready
- Hyper-threading solves this problem by introducing  $k$  *logical cores*
  - Each physical core may be mapped to  $k$  logical cores (e.g. 2)
  - A logical core looks like a core to the operating system
  - The CPU may interleave instructions from separate processes/threads in the same core, since they are more likely to be independent

# Hyper-threading

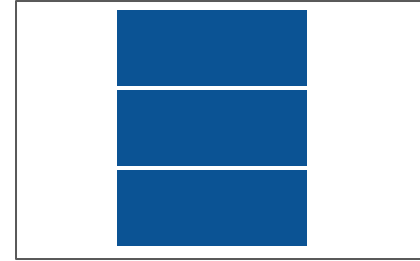
Process 1, Logical core 1



Physical core

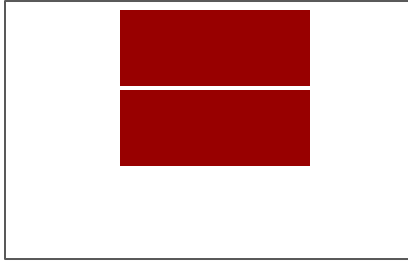


Process 2, Logical core 2



# Hyper-threading

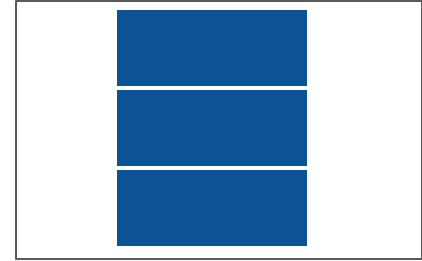
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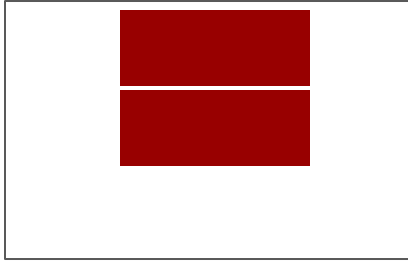


Process 2, Logical core 2



# Hyper-threading

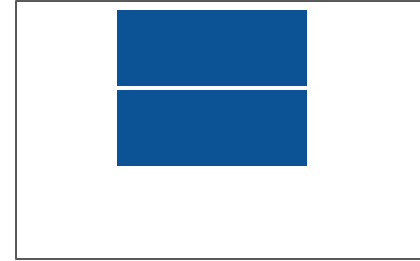
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Physical core

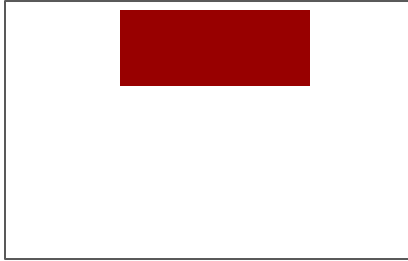


Process 2, Logical core 2

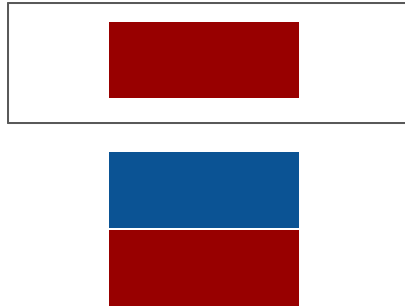


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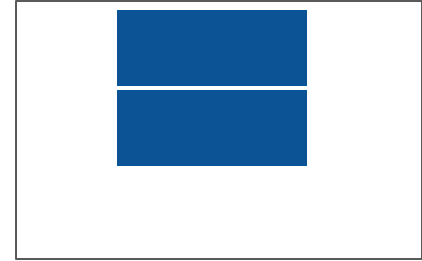
Process 1, Logical core 1



Physical core

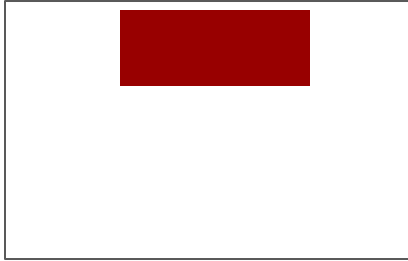


Process 2, Logical core 2

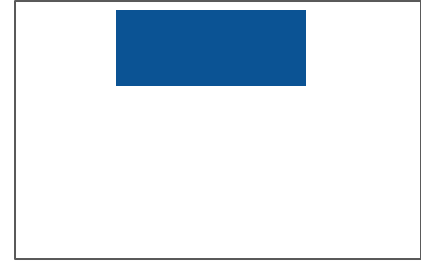


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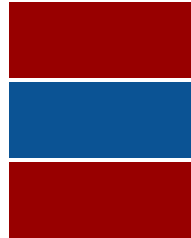
Process 1, Logical core 1



Process 2, Logical core 2

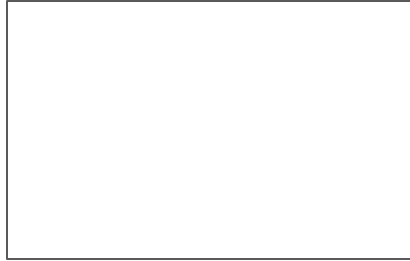


Physical core

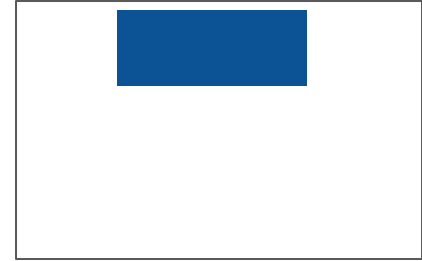


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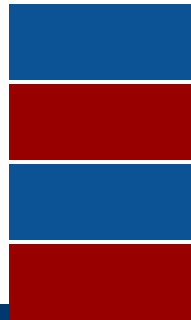
Process 1, Logical core 1



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Physical core

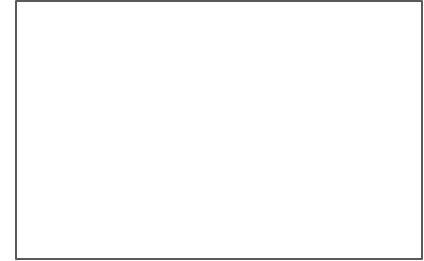


# Hyper-threading

Process 1, Logical core 1



Process 2, Logical core 2



Physical core



# Wrap-Up

- Optimizations
  - Pipelining
  - Hyperthreading

# What is next?

- Experiments with light
- Basic principles of quantum mechanics
  - Observer effect
  - Indeterminacy
  - Superposition
  - Entanglement
- Myths about quantum mechanics and quantum computing